Operating instructions





Welding machine

Tetrix 351 Synergic FW Tetrix 401 Synergic FW Tetrix 451 Synergic FW Tetrix 551 Synergic FW

099-000090-EW501

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07.11.2017

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General instructions

MARNING



Read the operating instructions!

The operating instructions provide an introduction to the safe use of the products.

- Read and observe the operating instructions for all system components, especially the safety instructions and warning notices!
- Observe the accident prevention regulations and any regional regulations!
- The operating instructions must be kept at the location where the machine is operated.
- Safety and warning labels on the machine indicate any possible risks. Keep these labels clean and legible at all times.
- The machine has been constructed to state-of-the-art standards in line with any applicable regulations and industrial standards. Only trained personnel may operate, service and repair the machine.
- Technical changes due to further development in machine technology may lead to a differing welding behaviour.



In the event of queries on installation, commissioning, operation or special conditions at the installation site, or on usage, please contact your sales partner or our customer service department on +49 2680 181-0.

A list of authorised sales partners can be found at www.ewm-group.com.

Liability relating to the operation of this equipment is restricted solely to the function of the equipment. No other form of liability, regardless of type, shall be accepted. This exclusion of liability shall be deemed accepted by the user on commissioning the equipment. The manufacturer is unable to monitor whether or not these instructions or the conditions and methods are observed during installation, operation, usage and maintenance of the equipment. An incorrectly performed installation can result in material damage and injure persons as a result. For this reason, we do not accept any responsibility or liability for losses, damages or costs arising from incorrect installation, improper operation or incorrect usage and maintenance or any actions connected to this in any way.

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2 For your safety

2.1 Notes on the use of these operating instructions

▲ DANGER

Working or operating procedures which must be closely observed to prevent imminent serious and even fatal injuries.

- · Safety notes include the "DANGER" keyword in the heading with a general warning symbol.
- The hazard is also highlighted using a symbol on the edge of the page.

MARNING

Working or operating procedures which must be closely observed to prevent serious and even fatal injuries.

- Safety notes include the "WARNING" keyword in the heading with a general warning symbol.
- The hazard is also highlighted using a symbol in the page margin.

▲ CAUTION

Working or operating procedures which must be closely observed to prevent possible minor personal injury.

- The safety information includes the "CAUTION" keyword in its heading with a general warning symbol.
- · The risk is explained using a symbol on the edge of the page.

Special technical points which users must observe.

Instructions and lists detailing step-by-step actions for given situations can be recognised via bullet points, e.g.:

Insert the welding current lead socket into the relevant socket and lock.

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2.2 Explanation of icons

| Symbol | Description S | | Description |
|------------|---|--------|---------------------------------|
| | Indicates technical aspects which the user must observe. | | Activate and release/tap/tip |
| | Switch off machine | | Release |
| 0 | Switch on machine | | Press and keep pressed |
| | | | Switch |
| | Wrong | | Turn |
| | Correct | | Numerical value – adjustable |
| ENTER | Menu entry | | Signal light lights up in green |
| NAVIGATION | Navigating the menu | ••••• | Signal light flashes green |
| EXIT | Exit menu | -;- | Signal light lights up in red |
| 45 | Time representation (e.g.: wait 4 s/activate) | •••••• | Signal light flashes red |
| -//- | Interruption in the menu display (other setting options possible) | | |
| *** | Tool not required/do not use | | |
| | Tool required/use | | |



2.3 Part of the complete documentation

F

These operating instructions are part of the complete documentation and valid only in combination with all other parts of these instructions! Read and observe the operating instructions for all system components, especially the safety instructions!

The illustration shows a general example of a welding system.

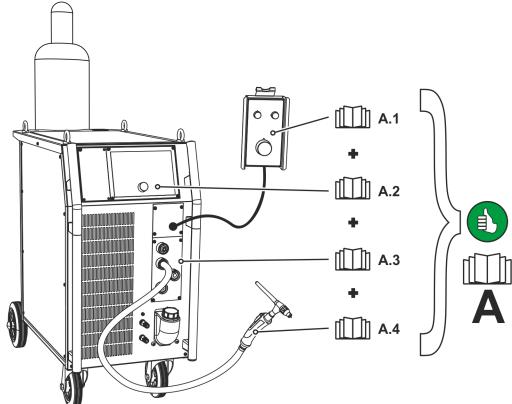


Figure 2-1

| Item | Documentation | |
|------|------------------------|--|
| A.1 | Remote control | |
| A.2 | Control | |
| A.3 | Power source | |
| A.4 | Welding torch | |
| A | Complete documentation | |

2.4 Safety instructions



▲ WARNING

Risk of accidents due to non-compliance with the safety instructions! Non-compliance with the safety instructions can be fatal!

- Carefully read the safety instructions in this manual!
- Observe the accident prevention regulations and any regional regulations!
- Inform persons in the working area that they must comply with the regulations!



▲ WARNING



Risk of injury from electrical voltage!

Voltages can cause potentially fatal electric shocks and burns on contact. Even low voltages can cause a shock and lead to accidents.

- Never touch live components such as welding current sockets or stick, tungsten or wire electrodes!
- Always place torches and electrode holders on an insulated surface!
- Wear the full personal protective equipment (depending on the application)!
- The machine may only be opened by qualified personnel!



Hazard when interconnecting multiple power sources!

If a number of power sources are to be connected in parallel or in series, only a technical specialist may interconnect the sources as per standard *IEC 60974-9:2010:*Installation and use and German Accident Prevention Regulation BVG D1 (formerly VBG 15) or country-specific regulations.

Before commencing arc welding, a test must verify that the equipment cannot exceed the maximum permitted open circuit voltage.

- Only qualified personnel may connect the machine.
- When taking individual power sources out of operation, all mains and welding current leads
 must be safely disconnected from the welding system as a whole. (Hazard due to reverse
 polarity voltage!)
- Do not interconnect welding machines with pole reversing switch (PWS series) or machines for AC welding since a minor error in operation can cause the welding voltages to be combined, which is not permitted.



Risk of injury due to improper clothing!

During arc welding, radiation, heat and voltage are sources of risk that cannot be avoided. The user has to be equipped with the complete personal protective equipment at all times. The protective equipment has to include:

- Respiratory protection against hazardous substances and mixtures (fumes and vapours);
 otherwise implement suitable measures such as extraction facilities.
- Welding helmet with proper protection against ionizing radiation (IR and UV radiation) and heat
- Dry welding clothing (shoes, gloves and body protection) to protect against warm environments with conditions comparable to ambient temperatures of 100 °C or higher and arcing and work on live components.
- Hearing protection against harming noise.



Risk of injury due to radiation or heat!

Arc radiation can lead to skin and eye injuries.

Contact with hot workpieces and sparks can lead to burns.

- Use hand shield or welding helmet with the appropriate safety level (depends on the application).
- Wear dry protective clothing (e.g. hand shield, gloves, etc.) in accordance with the applicable regulations of your country.
- Persons who are not directly involved should be protected with a welding curtain or suitable safety screen against radiation and the risk of blinding!



Explosion risk!

Apparently harmless substances in closed containers may generate excessive pressure when heated.

- Move containers with inflammable or explosive liquids away from the working area!
- Never heat explosive liquids, dusts or gases by welding or cutting!



MARNING



Fire hazard!

Due to the high temperatures, sparks, glowing parts and hot slag that occur during welding, there is a risk of flames.

- Be watchful of potential sources of fire in the working area!
- Do not carry any easily inflammable objects, e.g. matches or lighters.
- Ensure suitable fire extinguishers are available in the working area!
- Thoroughly remove any residue of flammable materials from the workpiece prior to starting to weld.
- Only further process workpieces after they have cooled down. Do not allow them to contact any flammable materials!

A CAUTION



Smoke and gases!

Smoke and gases can lead to breathing difficulties and poisoning. In addition, solvent vapour (chlorinated hydrocarbon) may be converted into poisonous phosgene due to the ultraviolet radiation of the arc!

- · Ensure that there is sufficient fresh air!
- Keep solvent vapour away from the arc beam field!
- Wear suitable breathing apparatus if appropriate!



Noise exposure!

Noise exceeding 70 dBA can cause permanent hearing damage!

- Wear suitable ear protection!
- Persons located within the working area must wear suitable ear protection!



According to IEC 60974-10, welding machines are divided into two classes of electromagnetic compatibility (the EMC class can be found in the Technical data) > see 8 chapter:



Class A machines are not intended for use in residential areas where the power supply comes from the low-voltage public mains network. When ensuring the electromagnetic compatibility of class A machines, difficulties can arise in these areas due to interference not only in the supply lines but also in the form of radiated interference.



Class B machines fulfil the EMC requirements in industrial as well as residential areas, including residential areas connected to the low-voltage public mains network.

Setting up and operating

When operating arc welding systems, in some cases, electro-magnetic interference can occur although all of the welding machines comply with the emission limits specified in the standard. The user is responsible for any interference caused by welding.

In order to **evaluate** any possible problems with electromagnetic compatibility in the surrounding area, the user must consider the following: (see also EN 60974-10 Appendix A)

- Mains, control, signal and telecommunication lines
- · Radios and televisions
- · Computers and other control systems
- · Safety equipment
- The health of neighbouring persons, especially if they have a pacemaker or wear a hearing aid
- Calibration and measuring equipment
- The immunity to interference of other equipment in the surrounding area
- · The time of day at which the welding work must be carried out

Recommendations for reducing interference emission

- Mains connection, e.g. additional mains filter or shielding with a metal tube
- Maintenance of the arc welding system
- · Welding leads should be as short as possible and run closely together along the ground
- Potential equalization
- Earthing of the workpiece. In cases where it is not possible to earth the workpiece directly, it should be connected by means of suitable capacitors.
- Shielding from other equipment in the surrounding area or the entire welding system





A CAUTION



Electromagnetic fields!

The power source may cause electrical or electromagnetic fields to be produced which could affect the correct functioning of electronic equipment such as IT or CNC devices, telecommunication lines, power cables, signal lines and pacemakers.



- Observe the maintenance instructions > see 6.3 chapter!
- Unwind welding leads completely!
- Shield devices or equipment sensitive to radiation accordingly!
- The correct functioning of pacemakers may be affected (obtain advice from a doctor if necessary).

Obligations of the operator!

The respective national directives and laws must be complied with when operating the machine!

- Implementation of national legislation relating to framework directive 89/391/EEC on the introduction of measures to encourage improvements in the safety and health of workers at work and associated individual guidelines.
- In particular, directive 89/655/EEC concerning the minimum safety and health requirements for the use of work equipment by workers at work.
- The regulations applicable to occupational safety and accident prevention in the country concerned.
- Setting up and operating the machine as per IEC 60974.-9.
- Brief the user on safety-conscious work practices on a regular basis.
- Regularly inspect the machine as per IEC 60974.-4.

The manufacturer's warranty becomes void if non-genuine parts are used!

- Only use system components and options (power sources, welding torches, electrode holders, remote controls, spare parts and replacement parts, etc.) from our range of products!
- Only insert and lock accessory components into the relevant connection socket when the machine is switched off.

Requirements for connection to the public mains network

High-performance machines can influence the mains quality by taking current from the mains network. For some types of machines, connection restrictions or requirements relating to the maximum possible line impedance or the necessary minimum supply capacity at the interface with the public network (Point of Common Coupling, PCC) can therefore apply. In this respect, attention is also drawn to the machines' technical data. In this case, it is the responsibility of the operator, where necessary in consultation with the mains network operator, to ensure that the machine can be connected.



2.5 Transport and installation

▲ WARNING



Risk of injury due to improper handling of shielding gas cylinders! Improper handling and insufficient securing of shielding gas cylinders can cause serious injuries!

- Observe the instructions from the gas manufacturer and any relevant regulations concerning the use of compressed air!
- Do not attach any element to the shielding gas cylinder valve!
- Prevent the shielding gas cylinder from heating up.

▲ CAUTION



Risk of accidents due to supply lines!

During transport, attached supply lines (mains leads, control cables, etc.) can cause risks, e.g. by causing connected machines to tip over and injure persons!

Disconnect all supply lines before transport!



Risk of tipping!

There is a risk of the machine tipping over and injuring persons or being damaged itself during movement and set up. Tilt resistance is guaranteed up to an angle of 10° (according to IEC 60974-1).

- Set up and transport the machine on level, solid ground.
- Secure add-on parts using suitable equipment.



Risk of accidents due to incorrectly installed leads!

Incorrectly installed leads (mains, control and welding leads or intermediate hose packages) can present a tripping hazard.

- Lay the supply lines flat on the floor (avoid loops).
- · Avoid laying the leads on passage ways.
- The units are designed for operation in an upright position!

 Operation in non-permissible positions can cause equipment damage.
 - Only transport and operate in an upright position!
- Accessory components and the power source itself can be damaged by incorrect connection!
 - Only insert and lock accessory components into the relevant connection socket when the machine is switched off.
 - Comprehensive descriptions can be found in the operating instructions for the relevant accessory components.
 - · Accessory components are detected automatically after the power source is switched on.
- Protective dust caps protect the connection sockets and therefore the machine against dirt and damage.
 - The protective dust cap must be fitted if there is no accessory component being operated on that connection.
 - · The cap must be replaced if faulty or if lost!



Intended use 3

▲ WARNING



Hazards due to improper usage!

The machine has been constructed to the state of the art and any regulations and standards applicable for use in industry and trade. It may only be used for the welding procedures indicated at the rating plate. Hazards may arise for persons, animals and material objects if the equipment is not used correctly. No liability is accepted for any damages arising from improper usage!

- The equipment must only be used in line with its designated purpose and by trained or expert personnel!
- Do not improperly modify or convert the equipment!

3.1 **Applications**

Arc welding machines for TIG DC welding with lift arc (touch starting) or HF ignition (contactless) and MMA welding as secondary process. It may be possible to expand the functionality by using accessories (see the documentation in the relevant chapter).

3.2 Documents which also apply

3.2.1 Warranty



For more information refer to the "Warranty registration" brochure supplied and our information regarding warranty, maintenance and testing at www.ewm-group.com!

3.2.2 **Declaration of Conformity**



The labelled machine complies with the following EC directives in terms of its design and construction:

- Low Voltage Directive (LVD)
- Electromagnetic Compatibility Directive (EMC)
- Restriction of Hazardous Substance (RoHS)

In case of unauthorised changes, improper repairs, non-compliance with specified deadlines for "Arc Welding Equipment – Inspection and Testing during Operation," and/or prohibited modifications which have not been explicitly authorised by the manufacturer, this declaration shall be voided. An original document of the specific declaration of conformity is included with every product.

3.2.3 Welding in environments with increased electrical hazards



In compliance with IEC / DIN EN 60974, VDE 0544 the machines can be used in environments with an increased electrical hazard.

3.2.4 Service documents (spare parts and circuit diagrams)



▲ WARNING

Do not carry out any unauthorised repairs or modifications!

To avoid injury and equipment damage, the unit must only be repaired or modified by specialist, skilled persons!

The warranty becomes null and void in the event of unauthorised interference.

Appoint only skilled persons for repair work (trained service personnel)!

Original copies of the circuit diagrams are enclosed with the unit.

Spare parts can be obtained from the relevant authorised dealer.

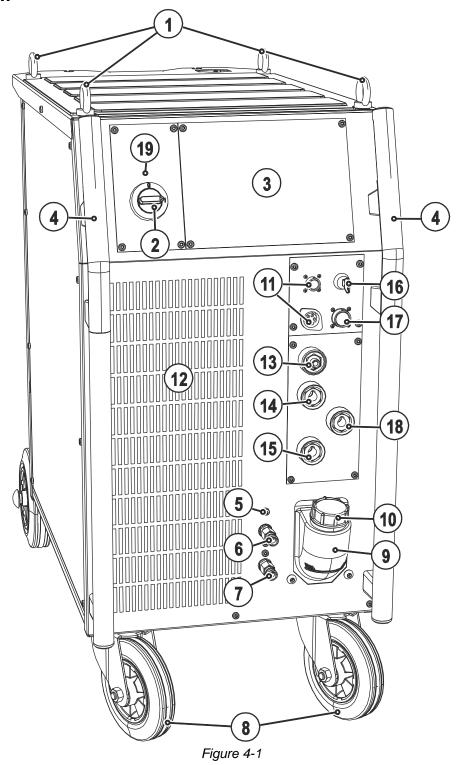
3.2.5 Calibration/Validation

We hereby confirm that this machine has been tested using calibrated measuring equipment, as stipulated in IEC/EN 60974, ISO/EN 17662, EN 50504, and complies with the admissible tolerances. Recommended calibration interval: 12 months



4 Machine description – quick overview

4.1 Front view





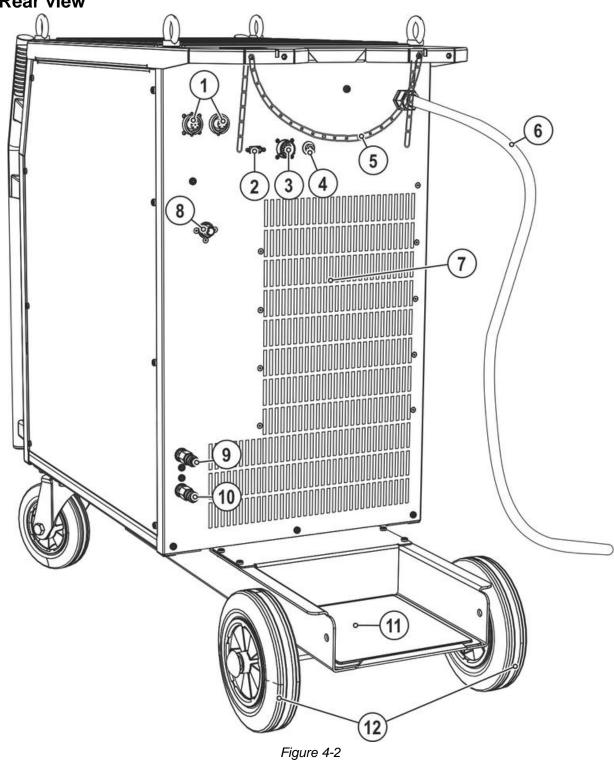




| Item | Symbol | Description |
|------|---------------|--|
| 1 | | Lifting lug |
| 2 | | Main switch, machine on/off |
| 3 | | Machine control > see 4.3 chapter |
| 4 | | Carrying handle |
| 5 | (A) | Automatic cut-out of coolant pump key button press to reset a triggered fuse |
| 6 | → | Quick connect coupling (red) coolant return |
| 7 | \Rightarrow | Quick connect coupling (blue) coolant supply |
| 8 | | Wheels, guide castors |
| 9 | | Coolant tank |
| 10 | | Coolant tank cap |
| 11 | | Connection socket, welding torch control cable > see 5.3.1.1 chapter |
| 12 | | Cooling air inlet |
| 13 | | G¼" connecting nipple, "-" welding current Shielding gas connection (with yellow insulating cap) for TIG welding torch |
| 14 | ₽ | Connection socket, "-" welding current TIG welding torch connection |
| 15 | + | Connection socket, "+" welding current Connection for workpiece lead |
| 16 | 0 1 | Key switch to protect against unauthorised use (retrofitting option) Position 1: changes possible. Position 0: no changes possible. > see 5.11 chapter. |
| 17 | 7 | Connection socket, 19-pole Remote control connection |
| 18 | 严 | Connection socket, "-" welding current Electrode holder connection |
| 19 | \otimes | Operating state signal lamp Lights up when the machine is ready for use. |



4.2 Rear view









| Item | Symbol | Description |
|------|---------------------|--|
| 1 | | Connection socket, 7-pole (digital) |
| | \leftrightarrow | To connect digital accessories |
| | ~ | Retrofitting option > see 9 chapter |
| 2 | COM | PC interface, serial (D-Sub connection socket, 9-pole) |
| 3 | 4 | Automation interface 19-pin (analogue) |
| | analog | Option for retrofitting > see 5.8.1 chapter |
| 4 |) *€ | Ignition type changeover switch > see 5.3.10 chapter |
| | $\langle 8 \rangle$ | =Liftarc (contact ignition) |
| | HF | HF = HF ignition |
| 5 | | Securing elements for shielding gas cylinder (strap/chain) |
| 6 | | Mains connection cable > see 5.1.7 chapter |
| 7 | | Cooling air outlet |
| 8 | Д⋈ | G¼" connecting nipple |
| | | Shielding gas connection on the pressure regulator. |
| 9 | | Quick connect coupling (red) |
| | 0 | coolant return |
| 10 | \bigcirc | Quick connect coupling (blue) |
| | O ' | coolant supply |
| 11 | | Bracket for shielding gas cylinder |
| 12 | | Wheels, fixed castors |



4.3 **Machine control – Operating elements**

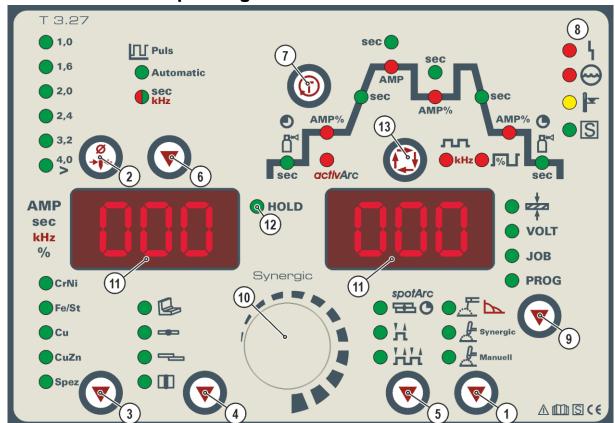


Figure 4-3

| Item | Symbol | Description | | |
|------|-------------|---|--|--|
| 1 | _ | "Welding process" button | | |
| | • | MMA welding, lights up in green / arcforce setting, lights up in red | | |
| | | ⊈⁵умети TIG synergic welding (synergic parameter setting) | | |
| | | TIG manual welding (manual parameter setting) | | |
| 2 | Ø | Electrode diameter push-button > see 5.4.2 chapter | | |
| | → ← | Ignition optimisation (TIG) > see 5.3.9 chapter | | |
| 3 | _ | "Select material type" button | | |
| | • | CrNi Chrome nickel alloys | | |
| | | FeSt Iron and steel alloys | | |
| | | Cu Copper or copper alloys (bronzes) | | |
| | | CuZn Copper zinc alloys (brass) | | |
| | | Spez Special (for special custom-built tasks) | | |
| 4 | | Select seam type button | | |
| | · | S Fillet weld | | |
| | | ➡ Butt joint | | |
| | | = Fillet weld - lap joint | | |
| | | | | |
| 5 | | Operating mode / Power-saving mode button | | |
| | • | spotArc | | |
| | | spotArc / spotmatic (spot time setting range) | | |
| | | h Non-latched | | |
| | | Latched | | |
| | | Press for 3 s to put machine into power-saving mode. To reactivate, activate one of the | | |
| | | operating elements > see 5.10 chapter. | | |

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| Item | Symbol | Description | | | |
|------|------------------------|--|--|--|--|
| 6 | ▼ 5 . | | | | |
| | , | Automatic TIG automated pulsing (frequency and balance) | | | |
| | | sec Little Signal light lights up in green: Pulsing (thermal pulsing)/MMA pulse welding | | | |
| | | Signal light lights up in red: kHz pulsing (metallurgical pulsing) | | | |
| 7 | ① | Gas test/rinse hose package button | | | |
| | | > see 5.3.2 chapter | | | |
| 8 | • \ | Error/status indicators | | | |
| | • 💮 | \\ Collective interference signal light | | | |
| | + | | | | |
| | • S | -Water deficiency signal light (welding torch cooling) | | | |
| | | FExcess temperature signal light | | | |
| | | ত্রS safety sign signal light | | | |
| 9 | | Display switching button | | | |
| | | Material thickness display | | | |
| | | VOLT Welding voltage display | | | |
| | JOB JOB number display | | | | |
| | | PROG Program number display | | | |
| 10 | | Welding parameter setting rotary dial | | | |
| | | Setting currents, times and parameters. | | | |
| 11 | [000] | Welding data display (3-digit) | | | |
| | رتاتات | Displays the welding parameters and the corresponding values > see 5.2 chapter | | | |
| 12 | Hold | Signal light Status display | | | |
| | | After each completed welding task, the last values used in the welding process for the | | | |
| | | welding current and welding voltage are shown on the displays, and the signal light will | | | |
| | | be on | | | |
| 13 | | Functional sequence > see 4.3.1 chapter | | | |

Function sequence 4.3.1

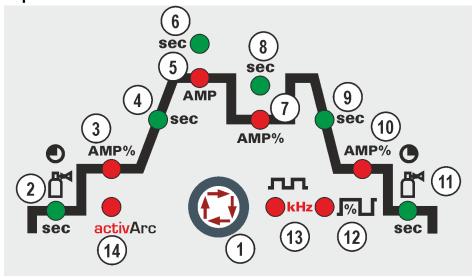
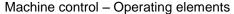


Figure 4-4

| Item | Symbol | Description | |
|------|----------|--|--|
| 1 | <u> </u> | Select welding parameters button | |
| | ↑ ↓ | Select welding parameters button This button is used to select the welding parameters depending on the welding process and operating mode used. | |
| | '←- | and operating mode used. | |

Machine description – quick overview Machine control – Operating elements





| Item | Symbol | Description | | | |
|------|-----------|---|--|--|--|
| 2 | 0 | Gas pre-flow time signal light [Pr] | | | |
| 3 | AMP% | Signal light Ignition current [5] (TIG)/hot start current [h] (MMA) | | | |
| 4 | sec | Signal light Up-slope time EUP (TIG)/hot start time EhE (MMA) | | | |
| 5 | AMP | Main current (TIG) / pulse current I min to I max (1 A increments) | Main current (MMA) I min to I max (1 A increments) | | |
| 6 | sec | Pulse time [1] / slope time [5] from AMP | % to AMP / Spot time | | |
| 7 | AMP% | Secondary current (TIG) | | | |
| 8 | sec | Pulse pause time £2 / slope time £52 fro The pulse time applies to the secondary curi | | | |
| 9 | sec | Down-slope time 🗺 signal light | | | |
| 10 | AMP% | End current signal light [Ed] | End current signal light [Ed] | | |
| 11 | | Gas post-flow time [PE] | | | |
| 12 | I%L | Balance signal light LAL Pulse balance | | | |
| 13 | лл kHz | Frequency signal light FcE Pulse frequency | | | |
| 14 | activArc | Signal light activArc RR > see 5.3.14 chapter | | | |



5 Design and function

▲ WARNING



Risk of injury from electrical voltage!

Contact with live parts, e.g. power connections, can be fatal!

- · Observe the safety information on the first pages of the operating instructions!
- Commissioning must be carried out by persons who are specifically trained in handling power sources!
- · Connect connection or power cables while the machine is switched off!

A CAUTION



Risk from electrical current!

If welding is carried out alternately using different methods and if a welding torch and an electrode holder remain connected to the machine, the open-circuit/welding voltage is applied simultaneously on all cables.

 The torch and the electrode holder should therefore always be placed on an insulated surface before starting work and during breaks.



Read and observe the documentation to all system and accessory components!

5.1 Transport and installation

5.1.1 Lifting by crane

▲ WARNING



Risk of injury during lifting by crane!

When lifting the machine by crane, persons may be severely injured by falling machines or mount-on components.

- Simultaneous lifting of system components such as power source, wire feeder or cooling unit without suitable crane components is not allowed. Each system component has to be lifted separately!
- Remove any supply leads and accessories before lifting by crane (e.g. hose package, wire spool, shielding gas cylinder, toolbox, wire feeder, remote control,etc.)!)
- Properly close and lock all casing covers and protective caps before lifting by crane!
- Use the correct number of hoisting equipment of the right size in the correct position! Observe craning principle (see figure)!
- · For machines with lifting eyes: always lift all lifting eyes simultaneously!
- When using retrofitted craning frames etc.: always use at least two lifting points positioned as far apart as possible – observe option description.
- Avoid any jerky movements!
- Ensure that the load is distributed evenly!
 Use chain hoists and chain slings of the same length only!
- Stay outside the danger zone underneath the machine!
- Observe the regulations regarding occupational safety and accident prevention for the respective country.



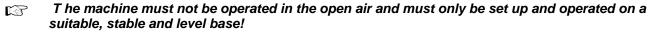
Craning principle

Design and function

Transport and installation



5.1.2 Ambient conditions



- The operator must ensure that the ground is non-slip and level, and provide sufficient lighting for the place of work.
- Safe operation of the machine must be guaranteed at all times.
- Unusually high quantities of dust, acid, corrosive gases or substances may damage the equipment.
 - · Avoid high volumes of smoke, vapour, oil vapour and grinding dust!
 - · Avoid ambient air containing salt (sea air)!

5.1.2.1 In operation

Temperature range of the ambient air:

-25 °C to +40 °C

Relative air humidity:

- Up to 50% at 40 °C
- Up to 90% at 20 °C

5.1.2.2 Transport and storage

Storage in an enclosed space, temperature range of the ambient air:

• -30 °C to +70 °C

Relative air humidity

Up to 90% at 20 °C

5.1.3 Machine cooling

Insufficient ventilation results in a reduction in performance and equipment damage.

- · Observe the ambient conditions!
- · Keep the cooling air inlet and outlet clear!
- Observe the minimum distance of 0.5 m from obstacles!

5.1.4 Workpiece lead, general



A CAUTION

Risk of burning due to incorrect welding current connection!

If the welding current plugs (machine connections) are not locked or if the workpiece connection is contaminated (paint, corrosion), these connections and leads can heat up and cause burns when touched!

- Check welding current connections on a daily basis and lock by turning to the right when necessary.
- Clean workpiece connection thoroughly and secure properly. Do not use structural parts of the workpiece as welding current return lead!

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5.1.5 Welding torch cooling system



Insufficient frost protection in the welding torch coolant!

Depending on the ambient conditions, different liquids are used for cooling the welding torch > see 5.1.5.1 chapter.

Coolants with frost protection (KF 37E or KF 23E) must be checked regularly to ensure that the frost protection is adequate to prevent damage to the machine or the accessory components.

- The coolant must be checked for adequate frost protection with the TYP 1 frost protection tester.
- · Replace coolant as necessary if frost protection is inadequate!

Coolant mixtures!

Mixtures with other liquids or the use of unsuitable coolants result in material damage and renders the manufacturer's warranty void!

- Only use the coolant described in this manual (overview of coolants).
- · Do not mix different coolants.
- When changing the coolant, the entire volume of liquid must be changed.

Dispose of the coolant in accordance with local regulations and the material safety data sheets (German waste code number: 70104).

May not be disposed of in household waste.

Prevent entry into sewers.

Absorb with liquid-binding material (sand, gravel, acid-binding agents, universal binding agents, sawdust).

5.1.5.1 Approved coolants overview

| Coolant | Temperature range |
|-------------------|-------------------|
| KF 23E (Standard) | -10 °C to +40 °C |
| KF 37E | -20 °C to +10 °C |

5.1.5.2 Maximal hose package length

| | Pump 3.5 bar | Pump 4.5 bar |
|---|--------------|--------------|
| Machines with or without separate wire feeder | 30 m | 60 m |
| Compact machines with additional intermediate drive (example. miniDrive) | 20 m | 30 m |
| Machines with separate wire feeder and additional intermediate drive (example: miniDrive) | 20 m | 60 m |

Data as a rule refer to the entire hose package length

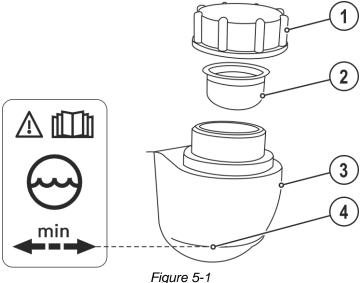
including welding torch. The pump output is shown on the type plate (parameter: Pmax).

Pump 3.5 bar: Pmax = 0.35 MPa (3.5 bar) Pump 4.5 bar: Pmax = 0.45 MPa (4.5 bar)



5.1.5.3 Adding coolant

The unit is supplied ex works with a minimum level of coolant.



| Item | Symbol | Description |
|------|--------|-----------------------|
| 1 | | Coolant tank cap |
| 2 | | Coolant filter sieve |
| 3 | | Coolant tank |
| 4 | | "Min" mark |
| | | Minimum coolant level |

- Unscrew and remove the coolant tank sealing cover.
- Check filter sieve insert for dirt, clean if necessary and reinsert into position.
- Top up coolant to the filter sieve insert, close sealing cover again.

If the cooling system is empty or only insufficiently filled with coolant, the coolant pump is automatically switched off after approx. one minute (protection against destruction). At the same time, the welding data display signals the lack of coolant or low coolant level.

- Reset the coolant error, fill coolant and repeat the operation.
- The level of coolant must never fall below the "min" mark. rigar Tigan
- If there is less coolant in the coolant tank than the minimum required you may need to vent the coolant circuit. In this case the welding machine will automatically shut down the coolant pump and signal an error, > see 7.6 chapter.



5.1.6 Notes on the installation of welding current leads

Incorrectly installed welding current leads can cause faults in the arc (flickering).

Lay the workpiece lead and hose package of power sources without HF igniter (MIG/MAG) for as long and as close as possible in parallel.

Lay the workpiece lead and hose package of power sources with HF igniter (TIG) for as long as possible in parallel with a distance of 20 cm to avoid HF sparkover.

Always keep a distance of at least 20 cm to leads of other power sources to avoid interferences Always keep leads as short as possible! For optimum welding results max. 30 m (welding lead + intermediate hose package + torch lead).

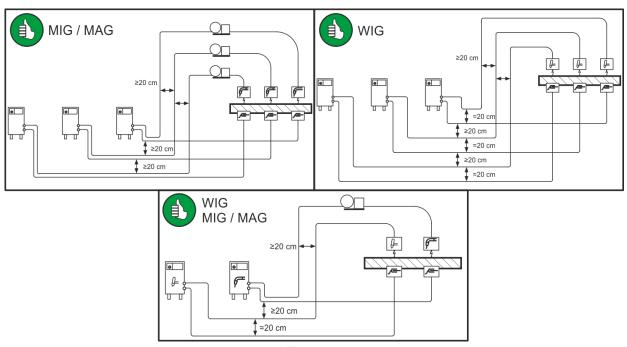


Figure 5-2

Use an individual welding lead to the workpiece for each welding machine!

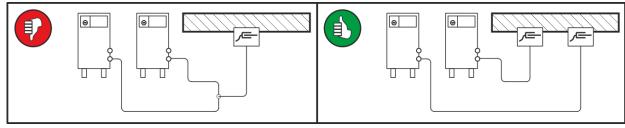


Figure 5-3

- Fully unroll welding current leads, torch hose packages and intermediate hose packages. Avoid loops!
- Always keep leads as short as possible!
- Lay any excess cable lengths in meanders.

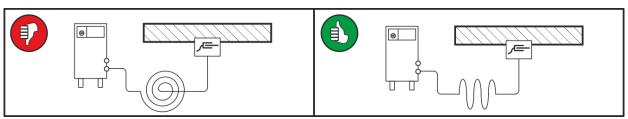


Figure 5-4

C)



5.1.6.1 Stray welding currents

4

▲ WARNING

Risk of injury due to stray welding currents!

Stray welding currents can destroy protective earth conductors, damage machines and electronic devices and cause overheating of components, leading to fire.

- Check that all welding current connections are firmly secured and electrical connections are in perfect condition.
- Set up, attach or suspend all conductive power source components such as casing, transport vehicles and crane frames so they are insulated.
- Do not place any other electronic devices such as drills or angle grinders on the power source, transport vehicle or crane frames unless they are insulated.
- Always put welding torches and electrode holders on an insulated surface when they are not in use.

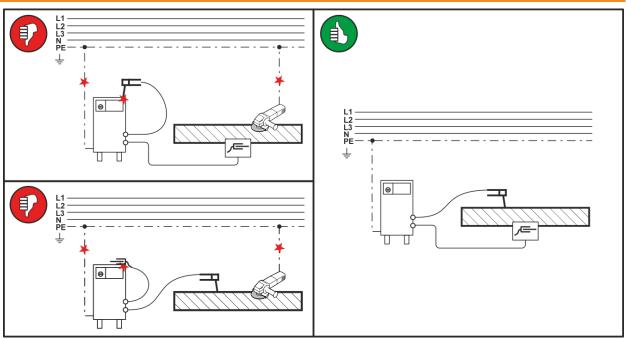


Figure 5-5

5.1.7 Mains connection



▲ DANGER

Hazards caused by improper mains connection!

An improper mains connection can cause injuries or damage property!

- Only operate machine using a socket that has correctly fitted protective earth.
- The mains voltage indicated on the rating plate must match the supply voltage.
- If a new mains plug must be fitted, only an electrician may do so as per the relevant national legislation or regulations.
- Mains plug, socket and lead must be checked by an electrician on a regular basis.
- When operating the generator, always ensure it is earthed as stipulated in the operating instructions. The network created must be suitable for operating machines according to protection class I.

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5.1.7.1 Mains configuration



The machine may be connected to:

- · a three-phase system with four conductors and an earthed neutral conductor
- a three-phase system with three conductors of which any one can be earthed, e.g. the outer conductor

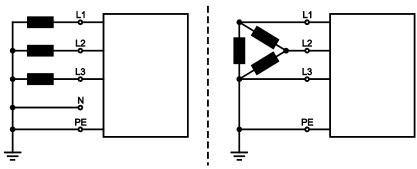


Figure 5-6

| Legend | | |
|--------|----------------------|--------------|
| Item | Designation | Colour code |
| L1 | Outer conductor 1 | brown |
| L2 | Outer conductor 2 | black |
| L3 | Outer conductor 3 | grey |
| N | Neutral conductor | blue |
| PE | Protective conductor | green-yellow |

· Insert mains plug of the switched-off machine into the appropriate socket.

5.2 Welding data display

The following welding parameters can be displayed before (nominal values), during (actual values) or after welding (hold values):

| left-hand display | | | |
|--------------------|---------------------------------|--------------------------------|-----------------------------|
| Parameter | Before welding (nominal values) | During welding (actual values) | After welding (hold values) |
| Welding current | Ø | \square | |
| Parameter times | Ø | | |
| Parameter currents | Ø | | |
| right-hand display | | | |
| Hot wire power | Ø | \square | |
| Welding voltage | Ø | Ø | ✓ |
| JOB number | Ø | | |
| Program number | | | |

When the settings are changed (e.g. welding current) after welding when the hold values are displayed, the display will be switched to the relevant nominal values.

If the "Program number" signal light is on in addition to the "Hot wire power" signal light, the user is in program mode > see 5.6 chapter.

If the "JOB-number" signal light is on in addition to the "Hot wire power" light, the user is in a JOB in the free memory > see 5.5.2 chapter.

Design and function

Welding data display



5.2.1 Welding parameter setting

During the welding parameter setting process, the parameter value being set is displayed on the left-hand display. The right-hand display shows the "Factory setting" or a variation of it upwards or downwards. Displays, e.g. when setting the ignition current, and their meanings:

| Display | Meaning of the symbols shown in the right-hand display |
|----------|---|
| | Increase parameter value To restore the factory settings. |
| <u> </u> | Factory setting Parameter value is on the optimum setting |
| 30 [-0 | Reduce parameter value To restore the factory settings. |

5.2.2 Setting the welding current (absolute/percentage)

The welding current for the ignition, secondary, end and hot start current can be set as a percentage of the main current AMP or as an absolute value. To select the display use the parameter his in the configuration menu <dg_ref_source_inline>Gerätekonfigurationsmenü</dg_ref_source_inline>.

> see 5.12 chapter

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TIG welding 5.3

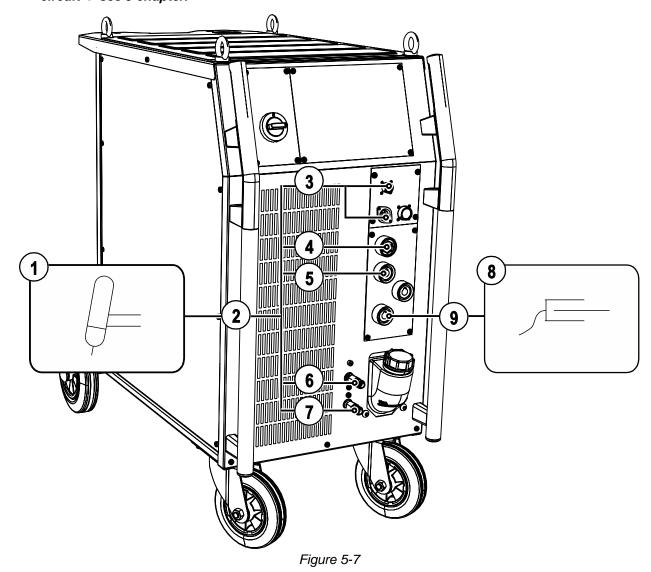
5.3.1 Welding torch and workpiece line connection

Prepare welding torch according to the welding task in hand (see operating instructions for the torch).

Equipment damage due to improperly connected coolant pipes!

If the coolant pipes are not properly connected or a gas-cooled welding torch is used, the coolant circuit is interrupted and equipment damage can occur.

- Connect all coolant pipes correctly!
- Completely unroll the hose package and the torch hose package!
- Observe maximal hose package length > see 5.1.5.2 chapter.
- When using a gas-cooled welding torch, use a hose bridge to establish the coolant circuit > see 9 chapter.



| Item | Symbol | Description |
|------|--------|--|
| 1 | ₽ | Welding torch |
| 2 | | Welding torch hose package |
| 3 | | Connection socket, welding torch control cable > see 5.3.1.1 chapter |
| 4 | | G¼" connecting nipple, "-" welding current Shielding gas connection (with yellow insulating cap) for TIG welding torch |

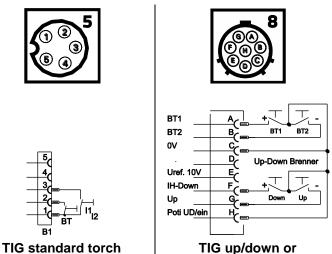


| Item | Symbol | Description |
|------|----------|--|
| 5 | Ω | Connection socket, "-" welding current TIG welding torch connection |
| 6 | → | Quick connect coupling (red) coolant return |
| 7 | → | Quick connect coupling (blue) coolant supply |
| 8 | | Workpiece |
| 9 | + | Connection socket, "+" welding current Connection for workpiece lead |

- Insert the welding current plug on the welding torch into the welding current connection socket and lock by turning to the right.
- Screw welding torch shielding gas connection tightly onto the G¼" connection nipple, welding current
 "-"
- Plug the welding torch control cable plug into the welding torch control cable connection socket and secure.
- Lock connecting nipples of the cooling water tubes into the corresponding quick connect couplings: Return line red to quick connect coupling, red (coolant return) and supply line blue to quick connect coupling, blue (coolant supply).
- Insert the cable plug on the work piece lead into the "+" welding current connection socket and lock by turning to the right.

5.3.1.1 Connection assignment, welding torch control cable

TIG welding machines are equipped ex works with a dedicated connection socket for the welding torch control cable (5- or 8-pole). As mobile machines offer more free space, they may even feature two control cable connection sockets. The functionality increases with the number of poles. One of these connection sockets may be converted or retrofitted > see 9 chapter.



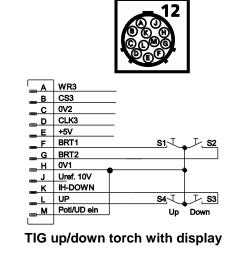


Figure 5-8

potentiometer torch

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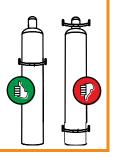


5.3.2 Shielding gas supply (shielding gas cylinder for welding machine)

▲ WARNING Risk of injury due to improper handling of shielding g

Risk of injury due to improper handling of shielding gas cylinders! Improper handling and insufficient securing of shielding gas cylinders can cause serious injuries!

- Place shielding gas cylinder into the designated holder and secure with fastening elements (chain/belt)!
- Attach the fastening elements within the upper half of the shielding gas cylinder!
- The fastening elements must tightly enclose the shielding gas cylinder!

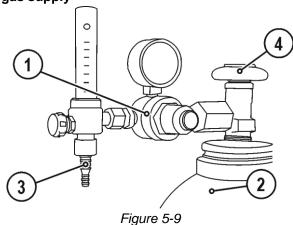




An unhindered shielding gas supply from the shielding gas cylinder to the welding torch is a fundamental requirement for optimum welding results. In addition, a blocked shielding gas supply may result in the welding torch being destroyed.

- Always re-fit the yellow protective cap when not using the shielding gas connection.
- · All shielding gas connections must be gas tight.

5.3.2.1 Connecting the shielding gas supply



| Item | Symbol | Description |
|------|--------|---------------------------------------|
| 1 | | Pressure regulator |
| 2 | | Shielding gas cylinder |
| 3 | | Output side of the pressure regulator |
| 4 | | Cylinder valve |

- Before connecting the pressure regulator to the gas cylinder, open the cylinder valve briefly to blow out any dirt.
- Tighten the pressure regulator screw connection on the gas bottle valve to be gas-tight.
- Screw gas hose connection crown nut onto the output side of the pressure regulator.
- Install gas hose with G1/4" crown nut at the correct welding machine connection

 so that it is gastight.



5.3.3 TIG Synergic operating principle

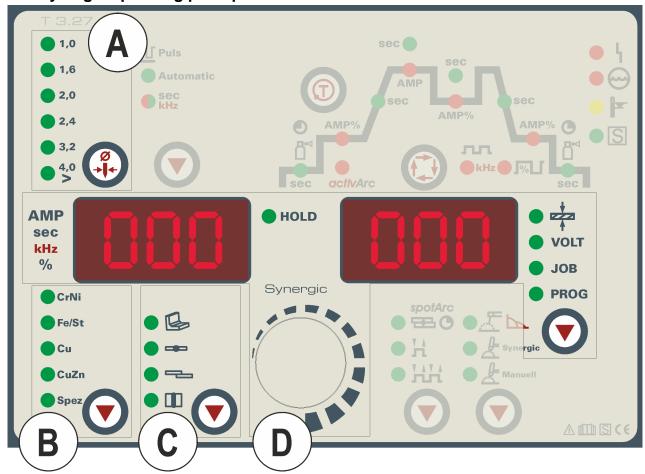


Figure 5-10

The machine is operated according to the TIG Synergic operating principle: In a similar way to the MIG machines with Synergic operation, three basic parameters –

- Tungsten electrode diameter (A),
- · Material type (B) and
- Seam type (C)

are used to select the welding task (JOB).

All welding parameters specified here are the optimum settings for a variety of applications, but they can also be modified individually.

The required welding current can be set as the sheet metal thickness or conventionally as the welding current (D).

The parameters and functions described here can also be programmed by PC using the Tetrix PC300.NET welding parameter software.

The Tetrix machine range has been designed to be very easy and quick to operate, whilst still providing all the functions one could ever need.



5.3.4 Synergic parameter setting in the functional sequence

When setting the welding current, all the necessary welding parameters are adjusted automatically during the functional sequence > see 4.3.1 chapter with the exception of the gas pre-flow time. These welding parameters can also be set in the conventional way if required (regardless of the welding current) > see 5.6.3 chapter.

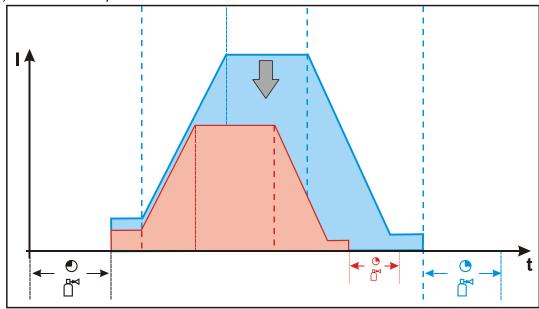


Figure 5-11

5.3.5 Conventional parameter setting in the functional sequence

All welding parameters in the functional sequence can also be adjusted, regardless of the welding current set. This means that if the welding current is changed, the values for the down slope time or gas post-flow time remain unchanged, for example. The welding task still needs to be selected as before using the three basic parameters of tungsten electrode diameter, material type and seam type.

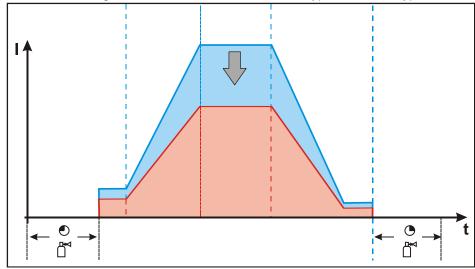


Figure 5-12

The parameters for the ignition, secondary and end currents can be set and displayed as percentage values or absolute values > see 5.12 chapter.

5.3.5.1 Set the operating principle (conventional/synergic)

The settings are defined in the machine configuration menu > see 5.12 chapter.



5.3.6 Welding task selection

The following welding task selection is an example of use. In general, the selection process always has the same sequence. Signal lights (LED) will show the selected combination.

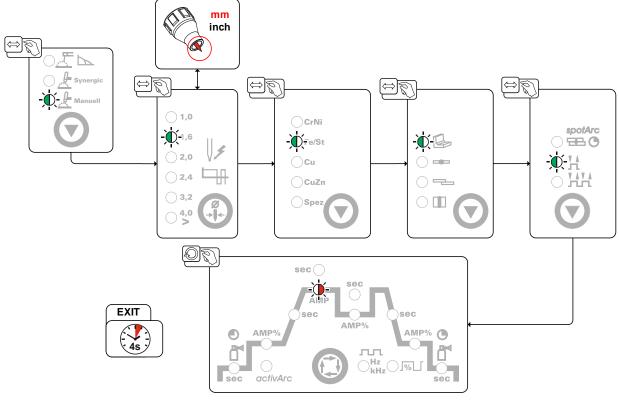


Figure 5-13

5.3.7 Select welding current

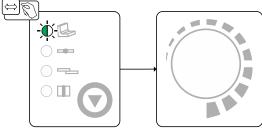


Figure 5-14

5.3.8 Gas test or "rinse hose package"

Rule of thumb for the gas flow rate:

Diameter of gas nozzle in mm corresponds to gas flow in I/min.

Example: 7mm gas nozzle corresponds to 7l/min gas flow.

If the shielding gas setting is too low or too high, this can introduce air to the weld pool and may cause pores to form. Adjust the shielding gas quantity to suit the welding task!

- Slowly open the gas cylinder valve. Conduct a gas test > see 5.3.8.1 chapter
- Set the required amount of shielding gas on the pressure reducer, about 4 15 l/min depending on the current strength and the material.



5.3.8.1 Gas test

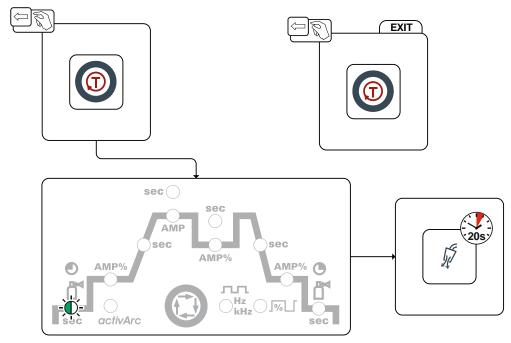


Figure 5-15

· Set the required shielding gas quantity at the pressure regulator.

5.3.8.2 "Purge hose package" function

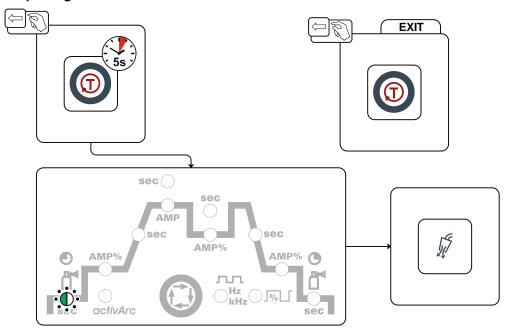


Figure 5-16

If the "Rinse hose package" function is not ended by pressing the "Gas and current parameters" button again, shielding gas will flow until the gas cylinder is empty!



5.3.9 Optimising the ignition characteristics for pure tungsten electrodes

The best ignition and stabilisation of the arc (DC, AC) and optimum spherical cup formation in the tungsten electrode depend on the electrode diameter being used.

The set value should correspond to the diameter of the tungsten electrode. The value can of course be adjusted in line with different requirements.

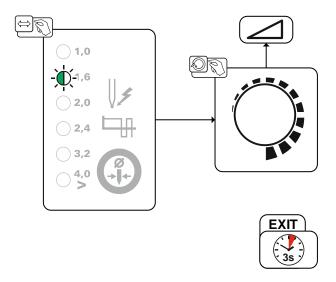


Figure 5-17

5.3.9.1 Tungsten balling function

Tungsten balling ensures optimum ignition and welding results for AC welding.

Optimum tungsten balling requires a sharpened electrode (about 15–25°) and the set electrode diameter on the machine control. The set electrode diameter affects the current for tungsten balling and, consequently, also the ball size.

Tungsten balling should be performed on a test component as surplus tungsten may be melted and this may lead to impurities on the weld seam.

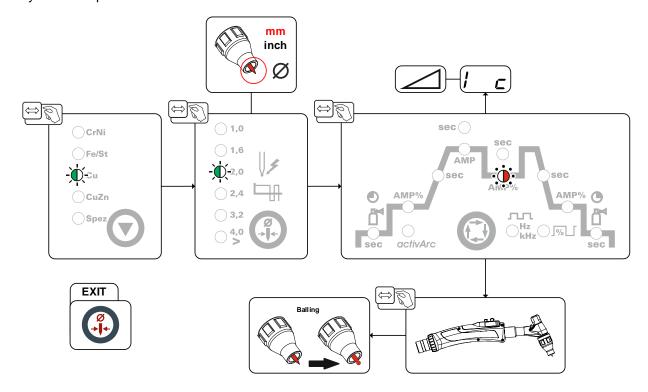


Figure 5-18



5.3.10 Arc ignition

5.3.10.1 HF ignition

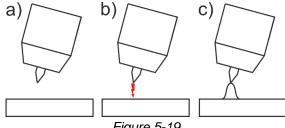


Figure 5-19

The arc is started without contact from high-voltage ignition pulses.

- a) Position the welding torch in welding position over the workpiece (distance between the electrode tip and workpiece should be approx. 2-3mm).
- b) Press the torch trigger (high voltage ignition pulses ignite the arc).
- c) Ignition current flows, and the welding process is continued depending on the operating mode selected.

End the welding process: Release or press the torch trigger depending on the operating mode selected.

5.3.10.2 Liftarc

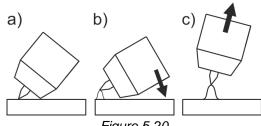


Figure 5-20

The arc is ignited on contact with the workpiece:

- a) Carefully place the torch gas nozzle and tungsten electrode tip onto the workpiece and press the torch trigger (liftarc current flowing, regardless of the main current set).
- b) Incline the torch over the torch gas nozzle to produce a gap of approx. 2-3 mm between the electrode tip and the workpiece. The arc ignites and the welding current is increased, depending on the operating mode set, to the ignition or main current set.
- c) Lift off the torch and swivel to the normal position.

Ending the welding process: Release or press the torch trigger depending on the operating mode selected.

5.3.10.3 Automatic cut-out

Once the fault periods have elapsed, the automatic cut-out stops the welding process when it has been triggered by one of two states:

- **During** ignition 3 s after the start of the welding process, no welding current flows (ignition error).
- **During welding**

The arc is interrupted for more than 3 s (arc interruption). You can disable or set the time for re-ignition after an arc interruption in the machine configuration menu > see 5.12 chapter (parameter [LA]).



5.3.11 Operating modes (functional sequences)

The parameters that can be set in the function sequence of the machine control depend on the selected welding task. This means that if for example you have not selected a pulse variant, then you cannot set any pulse times in the function sequence.

5.3.11.1 Explanation of symbols

| Symbol | Meaning | | |
|---------------|---|--|--|
| | Press torch trigger 1 | | |
| | Release torch trigger 1 | | |
| ı | Current | | |
| t | Time | | |
| • | Gas pre-flow | | |
| | | | |
| <u>[</u> [Pr] | | | |
| 1 5E | Ignition current | | |
| LUP | Up-slope time | | |
| L P | Spot time | | |
| | Main current (minimum to maximum current) | | |
| AMP | | | |
| 1 2 | Secondary current | | |
| AMP% | | | |
| <u> </u> | Pulse time | | |
| <u> </u> | Pulse pause time | | |
| Edn | Down-slope time | | |
| l Ed | End-crater current | | |
| • | Gas post-flow | | |
| | | | |
| <u>GPE</u> | | | |
| <u> </u> | Balance | | |
| FrE | Frequency | | |

5.3.11.2 Non-latched mode Selection

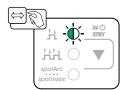
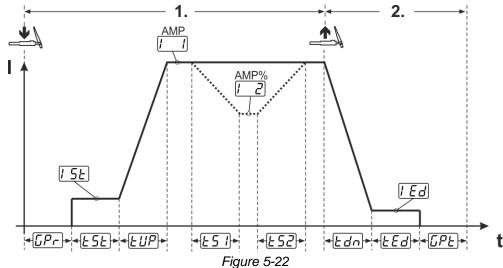


Figure 5-21







1st cycle:

- · Press torch trigger 1 and hold down.
- Gas pre-flow time **GPr** elapses.
- HF ignition pulses jump from the electrode to the workpiece. The arc ignites.
- The welding current flows and immediately assumes the value of the ignition current [5t].
- · HF switches off.
- The welding current ramps up to the main current [(AMP) in the selected up-slope time [].

If torch trigger 2 is pressed together with torch trigger 1 during the main current phase, the welding current decreases to the secondary current [2] (AMP%) in the set slope time [5].

If torch trigger 2 is released, the welding current increases again to the main current AMP in the set slope time £52. The parameters £51 and £52 can be set in the Expert menu (TIG) > see 5.3.15 chapter.

2nd cycle:

- · Release torch trigger 1.
- The main current falls to the end-crater current [Ed] (minimum current) in the set down-slope time [Ed]. If the 1st torch trigger is pressed during the down-slope time, the welding current returns to the set main current AMP
- Main current reaches the end-crater current **Ld**; the arc is extinguished.
- Set gas post-flow time [PE] elapses.

When the foot-operated remote control is connected, the machine switches automatically to non-latched operation. The up- and down-slopes are switched off.

5.3.11.3 Latched mode

Selection

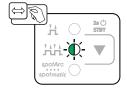
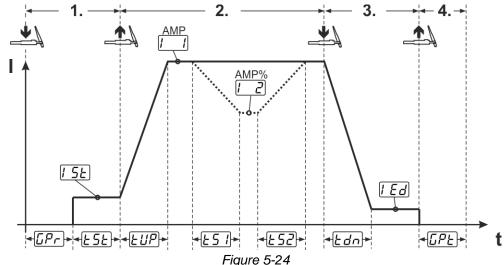


Figure 5-23



Sequence



1st cycle

- Press torch trigger 1 [Pr], the gas pre-flow time elapses.
- HF start pulses jump from the electrode to the workpiece. The arc ignites.
- Welding current flows and immediately assumes the set ignition current [5] (search arc at minimum setting). HF switches off.

2nd cycle

- Release torch trigger 1.
- The welding current ramps up to the main current (AMP) in the selected up-slope time (AMP).

Switching from the main current AMP to secondary current (AMP%):

- · Press torch trigger 2 or
- Tap torch trigger 1 (torch modes 1-6).

If torch trigger 2 is pressed together with torch trigger 1 during the main current phase, the welding current decreases to the secondary current (AMP%) in the set slope time (£51).

Once torch trigger 2 is released, the welding current increases again to the main current AMP in the set slope time $\boxed{\texttt{E52}}$. The parameters $\boxed{\texttt{E53}}$ and $\boxed{\texttt{E52}}$ can be set in the Expert menu (TIG) > see 5.3.15 chapter.

3rd cycle

- Press torch trigger 1.
- The main current decreases to the end-crater current [Ed] within the set down-slope time [Ed].

Once the main current phase AMP has been reached, you can shorten the welding sequence by tapping torch trigger 1 (third cycle will be omitted).

4th cycle

- · Release torch trigger 1; arc is extinguished.
- Set gas post-flow time GPE runs.

When the foot-operated remote control is connected, the machine switches automatically to non-latched operation. The up- and down-slopes are switched off.

Alternative welding start (tapping start):

For the alternative welding start, the durations of the first and second cycle are defined by the set process times only (tapping the torch trigger in the gas pre-low phase [Pr]).

To activate this function, set a two-digit torch mode (11-1x) at the machine control. This function can also be deactivated completely when required (welding stop by tapping remains active). To do so, the parameter must be switched to FF in the machine configuration menu > see 5.12 chapter.



5.3.11.4 spotArc

This process is suitable for tack welding or joint welding of metal sheets made from steel and CrNi alloys up to a thickness of approximately 2.5 mm. Metal sheets of different thicknesses can also be welded on top of one another. As this is a one-sided process, it is also possible to weld metal sheets onto tubular sections such as round or square pipes. In arc spot welding, the arc melts through the upper metal sheet and the lower metal sheet is melted onto it. This produces flat, fine-textured welding tacks which require little or no post weld work, even in visible areas.

The spot welding operating modes (spotArc/Spotmatic) can be used with two different intervals, i.e. a "long" or "short" interval, which are defined as follows:

| Interval | Setting range | Up-/down-slope | Pulsing | AC | Display | Display |
|----------|---------------------|-----------------------|---------|-----|---------------------|---------|
| Long | 0.01–20.0 s (10 ms) | Yes | Yes | Yes | 5£5 | of F |
| Short | 5–999 ms (1 ms) | No | No | No | 5 £ 5 | ٥ |

When selecting the spotArc operating mode, the long interval is automatically preselected. When selecting the Spotmatic operating mode, the short interval is automatically preselected. The user can change the interval in the Configuration menu > see 5.12 chapter.

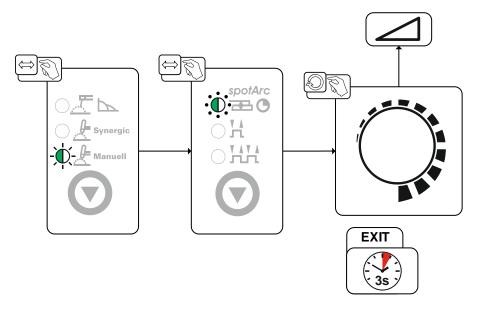
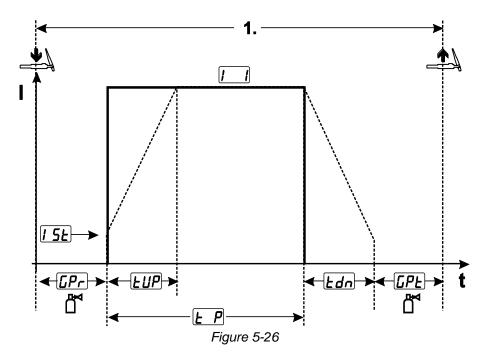


Figure 5-25

The up-slope and down-slope times should be set to "0" to achieve an effective result.





As an example the process is shown with HF ignition. Arc ignition with lift arc is also possible, however > see 5.3.10.2 chapter.

Sequence:

- · Press and hold torch trigger 1.
- The gas pre-flow time elapses.
- HF ignition pulses jump from the electrode to the workpiece, the arc ignites.
- The welding current flows and immediately assumes the value set for the ignition current [5].
- · HF is switched off.

The process ends when the set spotArc.time elapses or by releasing the torch trigger.

When switching on the spotArc function, Automatic pulsing is switched on as well. Any other pulsing variant can be selected as well, or no pulsing at all.

5.3.11.5 spotmatic

In contrast to the spotArc operating mode, the arc is not ignited by pressing the torch trigger as is usual, but by briefly touching the tungsten electrode against the workpiece. The torch trigger is used for welding process activation. Activation is indicated by flashing of the spotArc/spotmatic signal light. The process can be activated separately for each spot or also on a permanent basis. The setting is controlled using the 55P process activation parameter in the configuration menu > see 5.12 chapter.

- Separate process activation (55P > on):

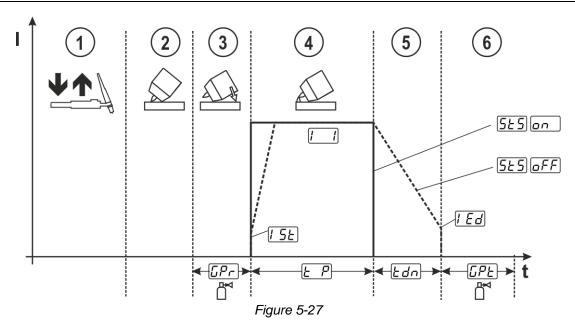
 The welding process has to be reactivated for every arc ignition by pressing the torch trigger. Process activation is automatically terminated after 30 s of inactivity.
- Permanent process activation (55P > 6FF):
 The welding process is activated by pressing the torch trigger once. The following arc ignitions are initiated by shortly touching the tungsten electrode against the workpiece. Process activation is terminated either by pressing the torch trigger again or automatically after 30 s of inactivity.

For spotmatic the separate process activation and the short spot time setting range are enabled by default.

Ignition by touching the tungsten electrode against the workpiece can be disabled in the machine configuration menu with parameter [577]. In this case the function works as with spotArc, but the spot time setting range can be selected in the machine configuration menu.

The duration is set in the machine configuration menu using parameter 555 > see 5.12 chapter





As an example the process is shown with HF ignition. Arc ignition with lift arc is also possible, however > see 5.3.10.2 chapter.

Selecting the process activation type for the welding process > see 5.12 chapter.

Up-slope and down-slope times possible for long spot time setting range (0.01–20.0 s) only.

- ① Press and release torch trigger (tap) to activate the welding process.
- ② Touch the torch gas nozzle and tungsten electrode tip carefully against the workpiece.
- 3 Incline the welding torch over the torch gas nozzle until there is a gap of approx. 2–3 mm between the electrode tip and the workpiece. Shielding gas flows during the set gas pre-flow time [P]. The arc ignites and the previously set ignition current [5] flows.
- ④ The main current phase ☐ ends when the set 戶 spot time elapses.
- (5) For long-time spot welding only (parameter (5£5) = [aff]):

 The welding current decreases to the end-crater current (£d) within the set down-slope time (£dn).
- © The gas post-flow time [PE] elapses and the welding process ends.

Press and release the torch trigger (tap) to reactivate the welding process (only for separate process activation). Touching the welding torch with the tungsten electrode tip against the workpiece again will initiate the next welding processes.



5.3.11.6 Non-latched operation, version C

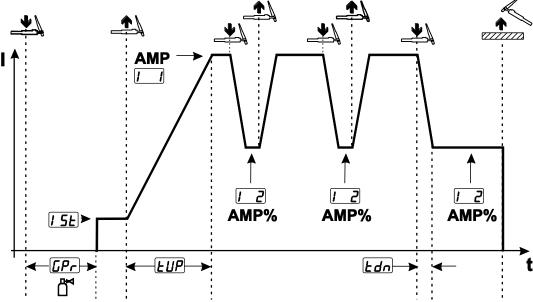


Figure 5-28

1st cycle

- Press torch trigger 1 [Pr], the gas pre-flow time elapses.
- HF ignition pulses jump from the electrode to the workpiece. The arc ignites.
- Welding current flows and immediately assumes the set ignition current [5] (search arc at minimum setting). HF switches off.

2nd cycle

- · Release torch trigger 1.
- The welding current ramps up to the main current AMP in the selected up-slope time EUP.

Pressing torch trigger 1 starts the slope £51 from main current AMP to secondary current £2 AMP%. Releasing the torch trigger starts the slope £52 from the secondary current AMP% and back to the main current AMP. This process can be repeated as frequently as required.

The welding process is stopped by interrupting the arc in the secondary current (remove the welding torch from the workpiece until the arc is extinguished, no re-ignition).

The slope times £51 and £52 can be set in the Expert menu > see 5.3.15 chapter.

This operating mode must be enabled (parameter [t]) > see 5.12 chapter.



5.3.12 Pulse welding

The following pulse types can be selected:

- Automated pulsing
- · Thermal pulsing
- · Metallurgical pulsing

5.3.12.1 Automated pulses

The automated pulses are used with tacking and spot welding of workpieces in particular. An oscillation in the molten pool is produced by the current-dependent pulse frequency and balance, which positively influences the ability to bridge the air gap. The pulse parameters required are automatically specified by the machine control.

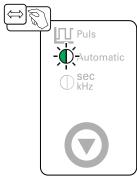
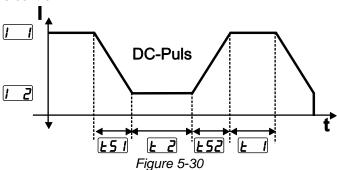


Figure 5-29

5.3.12.2 Thermal pulsing

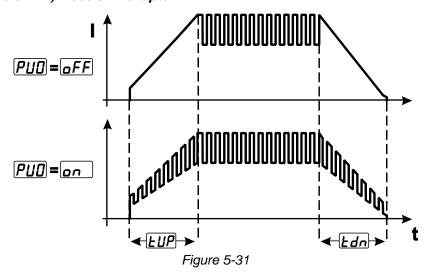
The operation sequences basically match the standard welding sequences, but there is an additional switching back and forth between the main current AMP (pulse current) and the secondary current AMP% (pulse pause current) at the set times. Pulse and pause times and the pulse edges (£51) and £52) are entered in seconds on the control.





F

The pulse function can also be deactivated if necessary during the up-slope and down-slope phases (parameter [III]) > see 5.12 chapter.



Selection

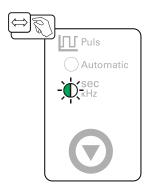


Figure 5-32



Pulse time setting

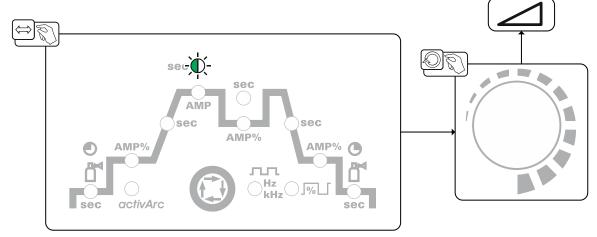


Figure 5-33

Pulse pause setting

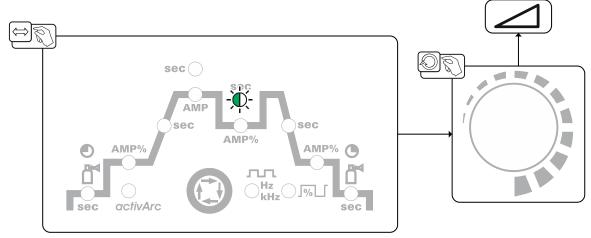


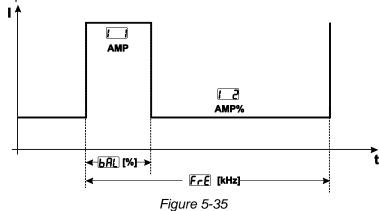
Figure 5-34

Pulse edge setting

The L51 and L52 pulse edges can be set in the Expert menu (TIG) > see 5.3.15 chapter.

5.3.12.3 Metallurgical pulsing (kHz pulsing)

Metallurgical pulsing (kHz pulsing) uses the plasma force (arc force) occurring at high currents which allows you to achieve a constricted arc with concentrated heat input. Unlike thermal pulsing, no times are set; a frequency FFE and the balance GFL are set instead. The pulsing process also occurs during the upslope and down-slope phase.





Selection

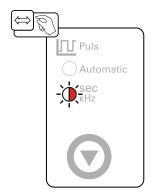


Figure 5-36

Balance setting

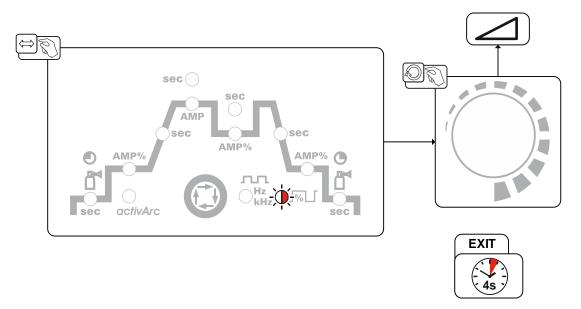


Figure 5-37

Frequency setting

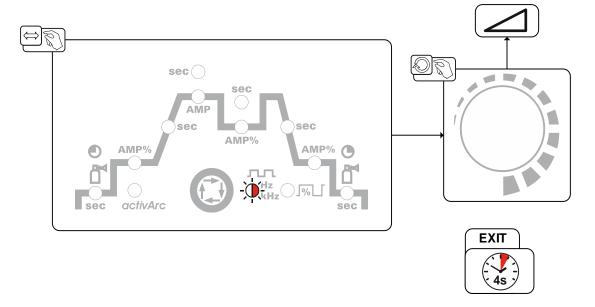


Figure 5-38



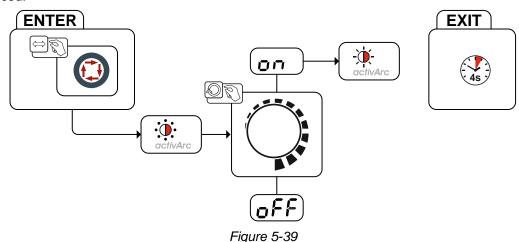
5.3.13 TIG antistick

The function prevents uncontrolled re-ignition following the sticking of the tungsten electrode in the weld pool by switching off the welding current. In addition, wear at the tungsten electrode is reduced.

After triggering the function the machine immediately switches to the gas post-flow process phase. The welder starts the new process again at the first cycle. The user can switch the function on or off (parameter [HS]) > see 5.12 chapter.

5.3.14 activArc

The EWM activArc process, thanks to the highly dynamic controller system, ensures that the power supplied is kept virtually constant in the event of changes in the distance between the welding torch and the weld pool, e.g. during manual welding. Voltage losses as a result of a shortening of the distance between the torch and molten pool are compensated by a current rise (ampere per volt - A/V), and vice versa. This helps prevents the tungsten electrode sticking in the molten pool and the tungsten inclusions are reduced.



Parameter setting

The activArc parameter (control) can be adjusted specifically for the welding task (panel thickness) > see 5.3.15 chapter.



5.3.15 Expert menu (TIG)

The Expert menu has adjustable parameters stored that don't require regular setting. The number of parameters shown may be limited, e.g. if a function is deactivated.

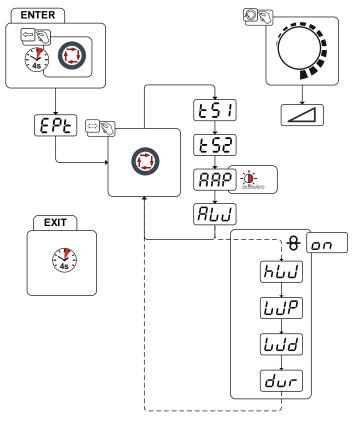


Figure 5-40

| Display | Setting/selection | |
|---|--|--|
| EPŁ | Expert menu | |
| £5 1 | Slope time (main current to secondary current) | |
| £52 | Slope time (main current to secondary current) | |
| 000 | activArc parameter | |
| ппг | Parameter also adjustable after TIG activArc welding is activated. | |
| Q_{II} | Filler wire process (cold/hot wire) | |
| נטטוט | en filler wire activated | |
| | <u>oFF</u> filler wire deactivated (factory setting) | |
| L 11 | Hot wire process (start signal for hot wire power source) | |
| נטטיט | Function enabled | |
| | <u>oFF</u> Function disabled (ex works) | |
| [IID] | Wire/pulse function (wire feeding behaviour when using pulsed TIG welding) | |
| Wire feeding can be disabled during pulse pauses (not the case for au | | |
| | pulsing or kHz pulsing). | |
| | en Function disabled | |
| | [aFF] Function enabled (ex works) | |





| Display | Setting/selection |
|---------|---|
| פרח | Filler wire diameter (manual setting) Setting the wire diameter between 0.6 mm to 1.6 mm. The character "d" preceding the wire diameter on the display (d0.8) indicates a preprogrammed characteristics (correction operating mode "KORREKTUR"). If there is no characteristics for the selected wire diameter, the parameters have to be set manually (manual operating mode "MANUELL"). To select the operating mode. |
| dur | Wire return Increase value = more wire return Decrease value = less wire return |

5.4 MMA welding

5.4.1 Connecting the electrode holder and workpiece lead



Risk of crushing and burns!

When changing stick electrodes there is a risk of crushing and burns!

- Wear appropriate and dry protective gloves.
- Use an insulated pair of tongs to remove the used stick electrode or to move welded workpieces.

▲ CAUTION



Shielding gas connection!

During MMA welding open circuit voltage is applied at the shielding gas connection (G½" connecting nipple).

• Place yellow insulating cap on the G¼" connection nipple (protects against electrical voltage and dirt).



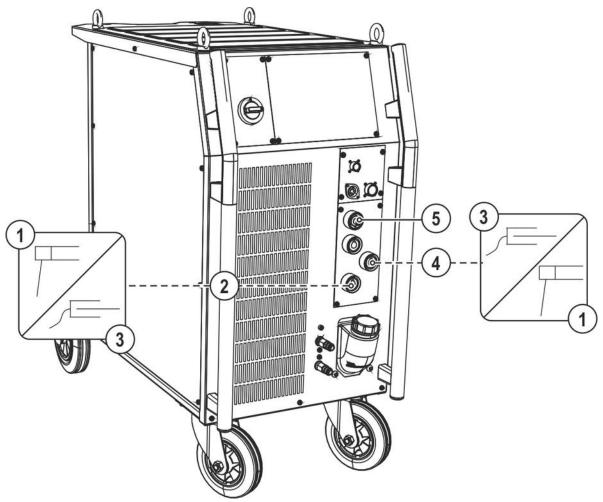


Figure 5-41

| Item | Symbol | Description |
|------|--------|---|
| 1 | | Workpiece |
| 2 | + | Connection socket, "+" welding current Connection for workpiece lead |
| 3 | F | Electrode holder |
| 4 | F- | Connection socket, "-" welding current Electrode holder connection |
| 5 | | G¼" connecting nipple Shielding gas connection (with yellow insulating cap) for TIG welding torch |



Polarity depends on the instructions from the electrode manufacturer given on the electrode packaging.

- Insert cable plug of the electrode holder into either the "+" or "-" welding current connection socket and lock by turning to the right.
- Insert cable plug of the workpiece lead into either the "+" or "-" welding current connection socket and lock by turning to the right.
- Fit yellow protective cap onto G1/4" connecting nipple.



5.4.2 Welding task selection

The following welding task selection is an example of use. In general, the selection process always has the same sequence. Signal lights (LED) will show the selected combination.

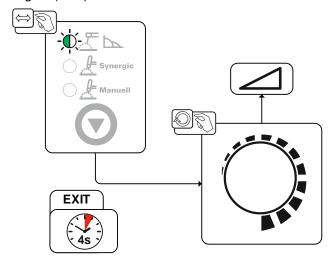


Figure 5-42

5.4.3 Hotstart

The hot start function improves the arc striking.

After striking the stick electrode, the arc ignites at the increased hot start current and decreases to the set main current once the hot start time has elapsed.

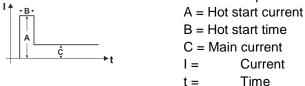


Figure 5-43

5.4.3.1 Hotstart current

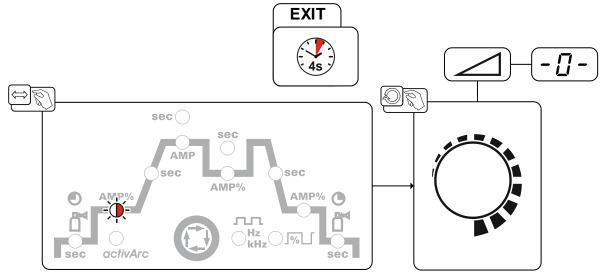


Figure 5-44



5.4.3.2 Hotstart time

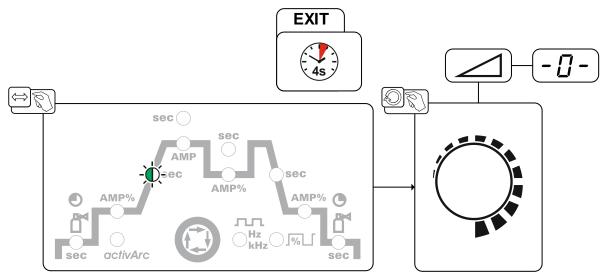


Figure 5-45

5.4.4 Arcforce

During the welding process, arcforce prevents the electrode sticking in the weld pool with increases in current. This makes it easier to weld large-drop melting electrode types at low current strengths with a short arc in particular.

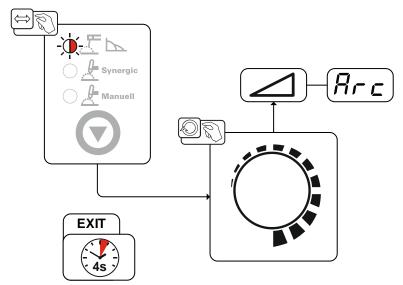
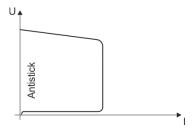


Figure 5-46

5.4.5 Antistick



The Antistick feature prevents the electrode from annealing.

Should the electrode stick despite the Arcforce feature, the machine automatically switches to the minimum current within approx. one second. This prevents the electrode from annealing. Check the welding current setting and correct for the welding task in hand.

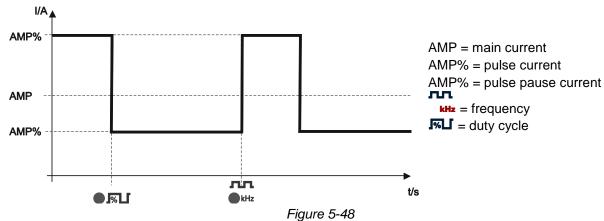
Figure 5-47



5.4.6 Average value pulsing in the vertical-up position (PF)

Welding characteristics:

- · Especially suitable for root welding
- · Fine-flaked weld surface with a TIG look for final passes
- · Less finishing work thanks to less spatter
- · Highly suitable for difficult electrodes
- · Outstanding gap bridging with no sagging of the root side
- · Less distortion thanks to controlled heat input



Selection

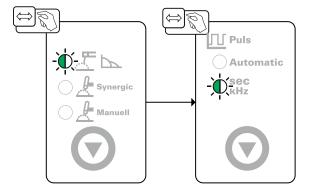


Figure 5-49

Pulse current setting

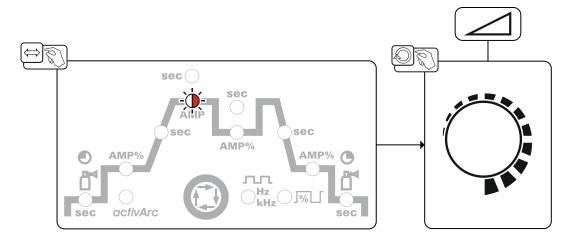


Figure 5-50



Pulse pause current setting

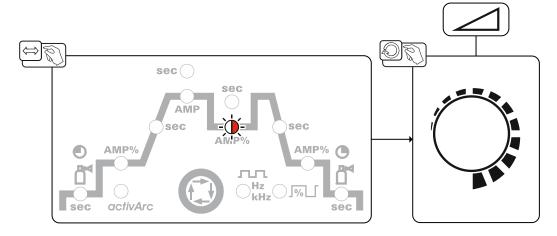


Figure 5-51

Balance setting

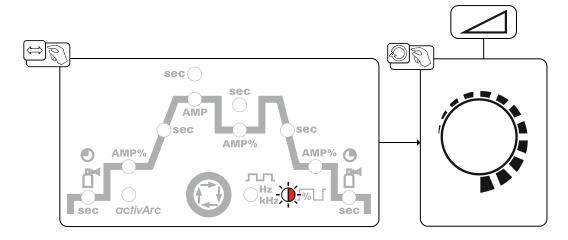


Figure 5-52

Frequency setting

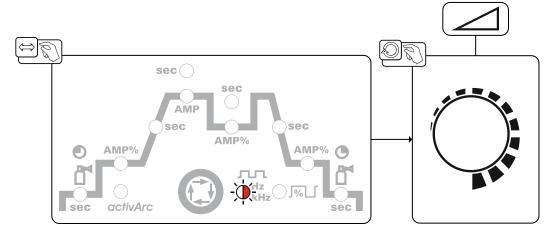


Figure 5-53

The default pulse parameters are pre-set in such a way that the welding current average value right 1 corresponds to the pre-selected main current AMP.

Changes in the pulse parameters result in changes to welding current average value AMP.







5.5 Organising welding tasks (Mode "JOB Manager")

T)

After carrying out any of the actions described, the machine switches back to the default parameters such as current and voltage.

To ensure that all the changes are active, the welding machine should only be switched off after 5 seconds have elapsed.

The JOB Manager can be used to load, copy or save JOBs.

A JOB is a welding task defined using the 4 main welding parameters

- welding process,
- · material type,
- · electrode diameter and
- · seam type.

One program sequence can be defined in each JOB.

Up to 16 programs (P0 to P15) can be set in each program sequence.

The user has a total of 249 JOBs available. 121 of these JOBs are pre-programmed. A further 128 JOBs can be freely defined.

A distinction is made between two memory sectors:

- 121 factory-set, pre-programmed, permanent JOBs. Permanent JOBs are not loaded but are defined by the welding task (each welding task is permanently assigned a JOB number).
- 128 freely definable JOBs (JOBs 129 to 256)

5.5.1 Explanation of symbols

| Display | Meaning |
|---------|----------------|
| Lad | Load JOB |
| caJ | Copy JOB |
| r E.J [| Reset JOB |
| r E.A [| Reset all JOBs |

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5.5.2 Creating a new JOB in the memory or copying a JOB

Copying a pre-defined welding task from the fixed memory (JOBs 1 to 128) to the free memory (JOBs 129-256):

It is normally possible to adjust all 256 JOBs individually. However, it is a good idea to assign specific JOB numbers in the free memory (JOB 128 to 256) for specific welding tasks.

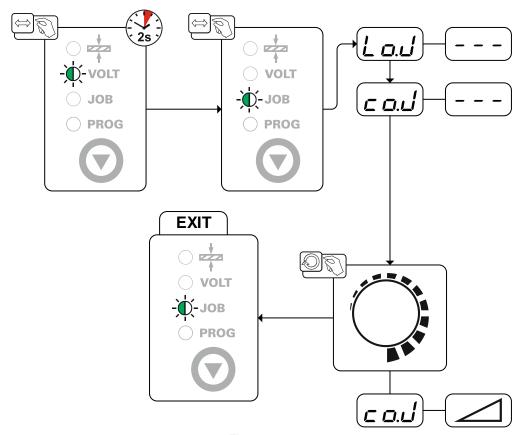


Figure 5-54



5.5.3 Loading an existing JOB from the free memory

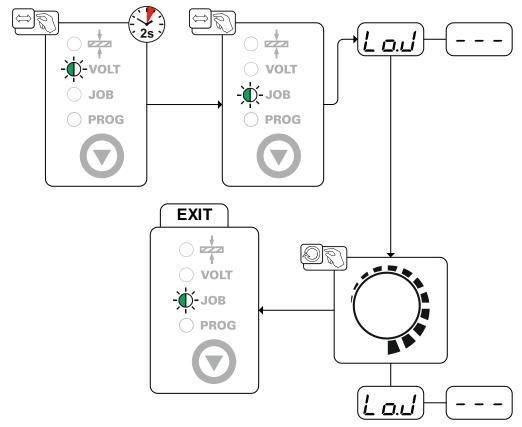


Figure 5-55

Resetting an existing JOB to the factory setting (Reset JOB) 5.5.4

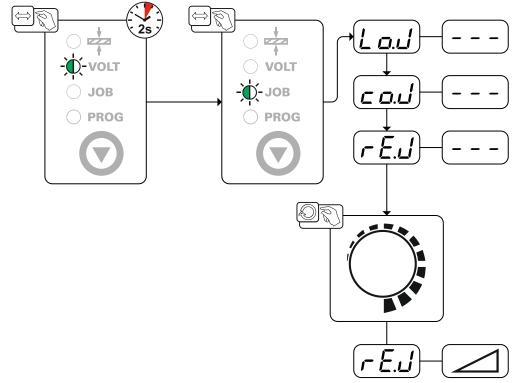
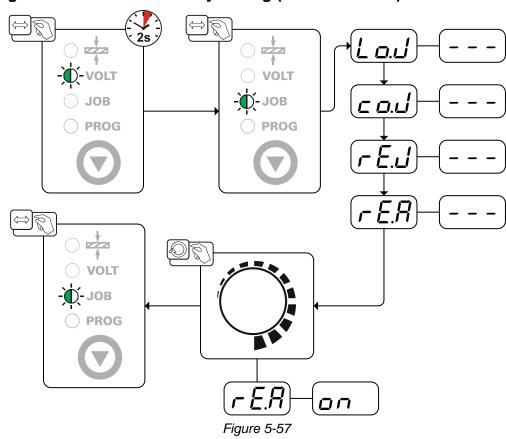


Figure 5-56



5.5.5 Resetting JOBs 1-128 to the factory setting (Reset All JOBs)



5.5.6 Exit JOB Manager without changes

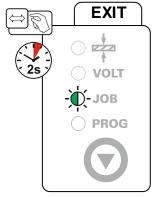


Figure 5-58

5.6 Welding programs

Changes made to the other welding parameters during the course of the program have the equivalent effect on all programs.

The change to the welding parameters is saved immediately in the JOB.

The welding machine has 16 programs, which you can change during welding.

In each selected welding task (JOB), > see 5.3.6 chapter, 16 programs can be set, saved and called up. In program "0" (default setting) the welding current can be infinitely adjusted across the entire range. In programs 1-15, 15 different welding currents (incl. operating mode and pulse function) are defined.

Example:

| Program number | Welding current | Operating mode | Pulse function |
|----------------|-----------------|----------------|----------------|
| 1 | 80A | Non-latched | Pulses on |
| 2 | 70A | Latched | Pulses off |



The operating mode cannot be changed during the welding process. If welding is started with program 1 (non-latched operating mode), program 2 controls the setting of ignition program 1 despite the latched setting and is implemented to the end of the welding process.

The pulse function (pulses off, pulses on) and the welding currents are transferred from the corresponding programs.

5.6.1 Selection and adjustment

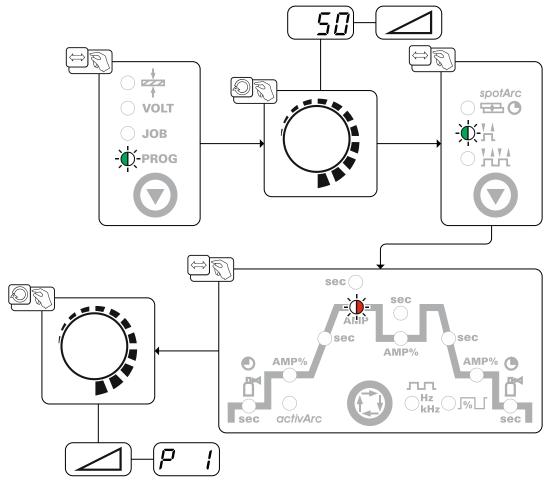
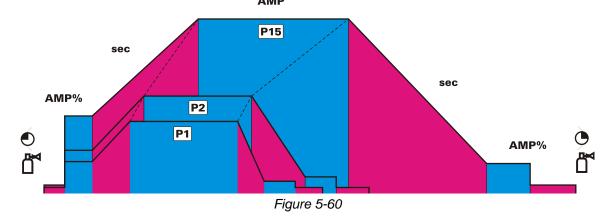


Figure 5-59

When connecting a potentiometer torch or up/down torch or operating a standard torch in up/down mode, the program changeover to the welding machine control is blocked!



5.6.2 Example "Program with synergetic setting"



5.6.3 Example "Program with conventional setting"

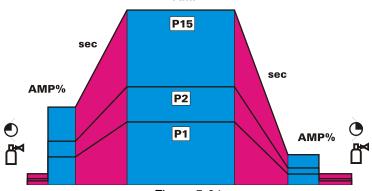


Figure 5-61

5.6.4 Accessories for switching over programs

The user can change, retrieve and save programs using the following components.

| | Progra | ms |
|---|-------------------|---------|
| Component | create and change | call up |
| Welding machine control | 16 | 16 |
| PC with PC 300 welding parameter software | 16 | 16 |
| Tablet PC RC 300 with PC 300 welding parameters | 16 | 16 |
| Tetrix RINT robot interface | - | 16 |
| BUSINT X10 industrial bus interface | - | 16 |

5.7 Remote control

The remote controls are operated on the 19-pole remote control connection socket (analogue).

5.7.1 RT1 19POL



Functions

• Infinitely adjustable welding current (0% to 100%) depending on the preselected main current on the welding machine.

5.7.2 RTG1 19POL



Functions

• Infinite setting of the welding current (0% to 100%) depending on the main current preselected at the welding machine



5.7.3 RTP1 19POL



Functions

- TIG/MMA
- Infinitely adjustable welding current (0% to 100%) depending on the preselected main current on the welding machine.
- Pulse/spot/normal
- · Pulse, spot and break times are infinitely adjustable.

5.7.4 RTP2 19POL



Functions

- TIG/MMA.
- Infinitely adjustable welding current (0% to 100%) depending on the preselected main current on the welding machine.
- Pulse/spot/normal
- Frequency and spot times infinitely adjustable.
- Coarse adjustment of the cycle frequency.
- Pulse/pause ratio (balance) adjustable from 10% to 90%.

5.7.5 RTP3 spotArc 19POL



Functions

- TIG / MMA.
- Infinitely adjustable welding current (0% to 100%) depending on the preselected main current on the welding machine.
- Pulse / SpotArc spots / normal
- Frequency and spot time infinitely adjustable.
- Coarse adjustment of the pulse frequency.
- Pulse/pause ratio (balance) adjustable from 10% to 90%.

5.7.6 RTF1 19POL



Functions

- Infinitely adjustable welding current (0% to 100%) depending on the preselected main current on the welding machine.
- Start/stop welding operation (TIG)

ActivArc welding is not possible in combination with the foot-operated remote control.



5.7.6.1 RTF start ramp

The RTF start ramp function prevents the energy input at the start of welding from being too high and too fast should the user press the remote control pedal too fast and too strongly.

Example:

The user sets the main current at the welding machine to 200 A. The user presses the remote control pedal very quickly down by approx. 50% of the pedal travel.

- RTF switched on: The welding current increases in a linear (slow)ramp to approx. 100 A.
- RTF switched off: The welding current immediately jumps to approx. 100 A.

The RTF start ramp function is activated/deactivated by the parameter FFF in the machine configuration menu > see 5.12 chapter.

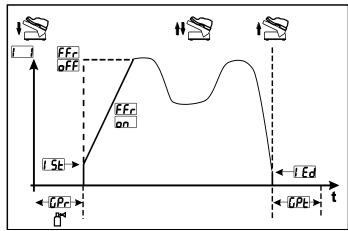


Figure 5-62

| Symbol | Meaning |
|--------------|--|
| 13 | Actuate foot-operated remote control (start welding process) |
| 11 | Operate foot-operated remote control (set welding current according to application) |
| 13 | Release foot-operated remote control (end welding process) |
| Display | Setting/selection |
| FFr | RTF start ramp > see 5.7.6.1 chapter Welding current rises to the specified main current level in a ramp function (ex works) Welding current immediately jumps to the specified main current level |
| [Pr | Gas pre-flow time |
| 15E | Ignition current (as percentage, dependent on main current) |
| | End-crater current |
| | Setting range in percent: depending on main current |
| | Setting range, absolute: Imin to Imax. |
| <u>[PE</u>] | Gas post-flow time |

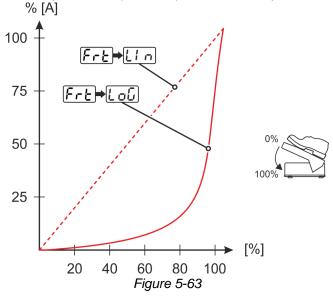
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5.7.6.2 RTF response

This function controls the current response during the main current phase. The user can choose between linear and logarithmic response. The logarithmic setting is especially suited for welding with low currents, e.g. for thin panels, as the logarithmic response enables a better control of the welding current.

In the machine configuration menu, the RTF response function Frecan be toggled between linear response [In] and logarithmic response [ac] (ex works) > see 5.12 chapter.



5.7.7 Welding torch (operating variants)

Different torch versions can be used with this machine.

Functions on the operating elements, such as torch triggers (BRT), rockers or potentiometers, can be modified individually via torch modes.

Explanation of symbols for operating elements:

| Symbol | Description |
|--|-----------------------------|
| ● BRT 1 <u>↓</u> | Press torch trigger |
| ● BRT 1 <u>Ū</u> <u>û</u> | Tap torch trigger |
| ●● BRT 2 <u>↓</u> <u>↑</u> ↑ <u>↓</u> | Tap and press torch trigger |

5.7.7.1 Tapping function (tap torch trigger)

Tapping function: Swiftly tap the torch trigger to change the function. The set torch mode determines the operating mode.

5.7.7.2 Torch mode setting

Modes 1 to 6 and 11 to 16 are available to the user. Modes 11 to 16 feature the same functionality as 1 to 6, but without the tapping function > see 5.12 chapter for the secondary current.

The functionality of the individual modes can be found in the corresponding torch type tables.

The torch modes are set using the torch configuration parameters "[-]" in the machine configuration menu > torch mode "[-]" > see 5.7.7.1 chapter.

Only the modes listed are suitable for the corresponding torch types.

Design and function

Remote control



5.7.7.3 Up/down speed

Functionality

Press and hold the up push-button:

Increase current up to the maximum value (main current) set in the power source.

Press and hold the down push-button:

Decrease current to the minimum value.

Use the machine configuration menu > see 5.12 chapter to set the up/down speed parameter which determines the speed with which a current change becomes effective.

5.7.7.4 Current jump

By tapping the corresponding torch trigger the welding current can be determined in an adjustable jump range. Each tap will cause the welding current to jump up or down by the defined value.

The "current jump" parameter is set in the machine configuration menu > see 5.12 chapter.

5.7.7.5 Standard TIG torch (5-pole)

Standard torch with one torch trigger

| Figure | Operating elements | Explanation of symbols | | |
|---------------------------------------|--------------------|---|------------|--------------------|
| 5 6 6 6 | | BRT1 = torch trigger 1 current via tapping fund | | /off; secondary |
| Functions | | | Mode | Operating elements |
| Welding current on/off | | | 1 | ● BRT 1 |
| Secondary current (latched operation) | | | (ex works) | ● BRT 1 |







Standard torch with two torch triggers

| Figure | Operating elements | Explanation of symbols |
|-----------|--------------------|--|
| 60 | | BRT1 = torch trigger 1 BRT2 = torch trigger 2 |

| Functions | Mode | Operating elements |
|--|-----------------|-----------------------------|
| Welding current on/off | | BRT 1- ● ● |
| Secondary current | 1 (ex works) | ●● BRT 2 |
| Secondary current (tapping function) ¹)/(latched operating mode) | | BRT 1- <u>Ū</u> Υ̂ |
| Welding current on/off | | BRT 1-●● <u>↓</u> |
| Secondary current (tapping function) ¹)/(latched operating mode) | 3 | BRT 1- <u>Ū</u> <u>û</u> |
| Up function ² | | ●● BRT 2 <u>Ū</u> Û Ū |
| Down function ² | | ●● BRT 2 |

¹ > see 5.7.7.1 chapter

² > see 5.7.7.3 chapter



Standard torch with one rocker (rocker, two torch triggers)

| Figure | Operating elements | Explanation of symbols |
|--------|--------------------|---|
| 5005 | | BRT 1 = torch trigger 1 BRT 2 = torch trigger 2 |

| Functions | Mode | Operating elements |
|--|-----------------|---------------------|
| Welding current on/off | | BRT 1 |
| Secondary current | 1 (ex works) | BRT 2 |
| Secondary current (tapping function) ¹)/(latched operating mode) | | BRT 1 |
| Welding current on/off | | BRT 1 + BRT 2 |
| Secondary current (tapping function ¹) | 2 | BRT 1 + BRT 2 |
| Up function ² | | BRT 1 |
| Down function ² | | BRT 2 |
| Welding current on/off | | BRT 1 |
| Secondary current (tapping function) ¹)/(latched operating mode) | | BRT 1 |
| Up function ² | 3 | ■ |
| Down function ² | | ■ BRT 2 |

¹ > see 5.7.7.1 chapter

² > see 5.7.7.3 chapter



5.7.7.6 TIG up/down torch (8-pole) Up/down torch with one torch trigger

| Image | Operating elements | Explanation of symbols |
|-------|--------------------|-------------------------|
| | | BRT 1 = torch trigger 1 |

| Functions | Mode | Operating elements |
|--|------------|--------------------|
| Welding current on/off | | ● BRT 1 |
| Secondary current (tapping function) ¹)/(latched operating mode) | 1 | ● BRT 1 |
| Increase welding current (up function ²) | (ex works) | U p |
| Decrease welding current (down function ²) | | Down |
| Welding current on/off | | ● BRT 1 |
| Secondary current | | ●● BRT 2 ■ |
| Secondary current (tapping function ¹) | 2 | BRT 1- ⊕⊕ |
| Program selection upwards | | Up |
| Program selection downwards | | Down |
| Welding current on/off | | ● BRT 1 |
| Secondary current (tapping function) ¹)/(latched operating mode) | | ● BRT 1 |
| Increase welding current via current jump ³ | 4 | Up |
| Decrease welding current via current jump ³ | | Down |

¹ > see 5.7.7.1 chapter

² > see 5.7.7.3 chapter

³ > see 5.7.7.4 chapter



Up/down torch with two torch triggers

| Figure Operating elements | | Explanation of symbols | |
|---------------------------|--|--|--|
| | | BRT 1 = torch trigger 1 (left) BRT 2 = torch trigger 2 (right) | |

| Functions | Mode | Operating elements |
|--|-----------------|--------------------|
| Welding current on/off | | BRT 1- |
| Secondary current | | ●● BRT 2 |
| Secondary current (tapping function) ¹ /(latched operation) | 1 (ex works) | BRT 1- ⊕û |
| Increase welding current (up function ²) | | Op Up |
| Decrease welding current (down function ²) | | Down |
| Welding current on/off | | BRT 1- ● ● |
| Secondary current | 2 | ●● BRT 2 |
| Secondary current (tapping function ¹) | | BRT 1- ⊕⊕ ⊕⊕ |
| Program selection upwards | | ● Up |
| Program selection downwards | | Down |
| Welding current on/off | | BRT 1- |
| Secondary current | | ●● BRT 2 |
| Secondary current (tapping function ¹) | 4 | BRT 1- ● ● ■ ■ |
| Increase welding current via current jump ³ | | Up Up |
| Decrease welding current via current jump ³ | | Down |
| Gas test | 4 | ●● BRT 2 |

¹ > see 5.7.7.1 chapter

² > see 5.7.7.3 chapter

³ > see 5.7.7.4 chapter



5.7.7.7 Potentiometer torch (8-pole)

B

The welding machine needs to be configured for operation with a potentiometer torch > see 5.7.7.8 chapter.

Potentiometer torch with one torch trigger

| Figure | Operating elements | Explanation of symbols |
|--------|--------------------|-------------------------|
| | | BRT 1 = torch trigger 1 |

| Functions | Mode | Operating elements |
|--|------|--------------------|
| Welding current on/off | 3 | BRT 1 |
| Secondary current (tapping function ¹) | | BRT 1 ŪÛ |
| Increase welding current | | |
| Decrease welding current | | |

Potentiometer torch with two torch triggers

| Figure | Operating elements | Explanation of symbols |
|--------|--------------------|---|
| | | BRT 1 = torch trigger 1 BRT 2 = torch trigger 2 |

| Functions | Mode | Operating elements |
|--|------|--------------------|
| Welding current on/off | | BRT 1- ● ● |
| Secondary current | | ●● BRT 2 |
| Secondary current (tapping function ¹) | 3 | BRT 1 ● |
| Increase welding current | | |
| Decrease welding current | | |

¹ > see 5.7.7.1 chapter



5.7.7.8 Configuring the TIG potentiometer torch connection

▲ DANGER



Risk of injury due to electrical voltage after switching off! Working on an open machine can lead to fatal injuries!

Capacitors are loaded with electrical voltage during operation. Voltage remains present for up to four minutes after the mains plug is removed.

- 1. Switch off machine.
- 2. Remove the mains plug.
- 3. Wait for at last 4 minutes until the capacitors have discharged!

▲ WARNING



Do not carry out any unauthorised repairs or modifications!

To avoid injury and equipment damage, the unit must only be repaired or modified by specialist, skilled persons!

The warranty becomes null and void in the event of unauthorised interference.

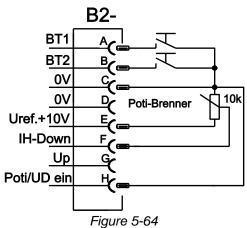
Appoint only skilled persons for repair work (trained service personnel)!



Before reconnection, "Inspection and Testing during Operation" according to IEC/BS EN 60974-4 "Arc welding systems – Inspection and Testing during Operation" has to be performed!

When connecting a potentiometer torch, jumper JP27 on PCB T320/1 inside the welding machine should be unplugged.

| Welding torch configuration | Setting |
|--|---------|
| Prepared for TIG standard or up/down torch (factory setting) | ☑ JP27 |
| Prepared for potentiometer torches | □ JP27 |



This torch type requires the welding machine to be set to torch mode 3 > see 5.7.7.2 chapter.

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TT 4

TT 2 (3 s)





5.7.7.9 RETOX TIG torch (12-pole)

For operation with this welding torch, the welding machine must be equipped with the retrofit option "ON 12POL RETOX TIG" (12-pole torch connection socket)!

| Diagram | Operating elements | Explanation of syr | nbols | |
|--|---------------------------|-----------------------|-----------------|--------------------|
| (S) | BRT 3 BRT 2 BRT 4 | TT= torch trigger | | |
| Functions | | | Mode | Operating elements |
| Welding current on/or | ff | | | TT 1 |
| Secondary current | | | 1 (ex works) | TT 2 |
| Secondary current (tapping function) | | | | TT 1 (tapping) |
| Increase welding current (up function) | | | | TT 3 |
| Reduce welding current (down function) | | | | TT 4 |
| Modes 2 and 3 are n | ot used with this type of | torch or, respectivel | y, are not ap | propriate. |
| Welding current on/of | ff | | | TT 1 |
| Secondary current | | | | TT 2 |
| Secondary current (tapping function) | | | | TT 1 (tapping) |
| Raise welding current in stages (setting the first increment) | | | | TT 3 |
| Decrease welding current in stages (setting the first decrement) | | | 4 | TT 4 |
| Switchover between Up-Down and JOB changeover | | | | TT 2 (tapping) |
| Increase JOB number | | | | TT 3 |

Decrease JOB number

Gas test

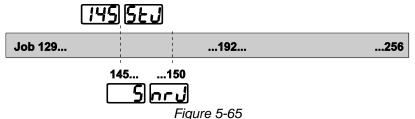


5.7.7.10 Specifying max. no. of accessible JOBs

This function can be used to specify the maximum number of JOBs which can be retrieved from the free memory. The factory setting is for 10 JOBs to be accessible on the welding machine, but this figure can be increased to up to 128 if required.

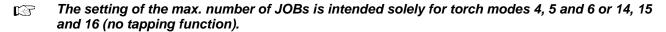
The first JOB in the free memory is JOB 129. With the factory setting of 10 JOBs, this equates to JOB numbers 129 to 138. The first JOB can be set as required.

The following graphic gives an example with the settings for max. JOBs available = 5 and first available JOB = 145. This gives the available JOBs 145 to 150.



| Display | Setting/selection | |
|---------------|--|--|
| | Start JOB | |
| <i>ال 5</i> 5 | Set first JOB to get (setting: 129 to 256, factory setting 129). | |
| | Get JOB number | |
| [חרט] | Set maximum selectable jobs (setting: 1 to 128, factory setting 10). | |
| | Additional parameter after activating the BLOCK JOB function. | |





5.8 Interfaces for automation



▲ WARNING

Do not carry out any unauthorised repairs or modifications!

To avoid injury and equipment damage, the unit must only be repaired or modified by specialist, skilled persons!

The warranty becomes null and void in the event of unauthorised interference.

• Appoint only skilled persons for repair work (trained service personnel)!

Damage to the machine due to improper connection!

Unsuitable control leads or incorrect connection of input and output signals can cause damage to the machine.

- Only use shielded control leads!
- If the machine is to be operated with control voltages connection via suitable isolation amplifiers is required!
- To control the main or secondary current via control voltages, the relevant inputs must be enabled (see specification for activation of control voltage).

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5.8.1 Automation interface

▲ WARNING



No function of the external interrupt equipment (emergency stop switch)! If the emergency stop circuit has been set up using an external interrupt equipment connected to the interface for automated welding, the machine must be configured for this setup. If this is not observed, the power source will ignore the external interrupt equipment and will not shut down!

• Remove jumper 1 on the T320/1, M320/1 or M321 PCB!

These accessory components can be retrofitted as an option > see 9 chapter.

| Pin | Signal shape | Designation | Diagram | |
|----------|--------------|--|-----------|-------------------------------|
| Α | Output | PE Connection for cable screen | | X6 |
| В | Output | REGaus For servicing purposes only | PE | Α _ |
| С | Input | SYN_E Synchronisation for master/slave operation | REGaus | B _ |
| D | Input | IGRO Current flows signal I>0 (maximum load 20mA | | C |
| | (no c.) | / 15V) 0V = welding current flowing | SYN_E | —(|
| E | Input | Not/Aus Emergency stop for higher level shut-down of | IGR0 | <u>D</u> $\stackrel{>}{\sim}$ |
| + | Impat | the power source. | Not/Aus | |
| R | Output | To use this function, jumper 1 must be unplugged on | 0V | |
| | | PCB T320/1 in the welding machine. Contact open = welding current off | NC | G $\stackrel{\frown}{>}$ |
| F | Output | 0V Reference potential | Uist | Н |
| G | - | NC Not assigned | VSchweiss | J |
| Н | Output | Uist Actual welding voltage, measured on pin F, 0- | SYN_A | K |
| | · | 10V (0V = 0V, 10V = 100V) | Str./Stp. | L |
| J | | Vschweiss Reserved for special purposes | +15V | M |
| K | Input | SYN_A Synchronisation for master/slave operation | 1 | —(|
| L | Input | Str/Stp Start / stop welding current, same as torch | -15V | $\frac{N}{2}$ |
| | | trigger. Only available in non-latched operating mode. +15V = | NC NC | P (|
| | | start, 0V = stop | Not/Aus | |
| M | Output | +15V Voltage supply | 0V | S |
| | | +15V, max. 75mA | list | T |
| N | Output | -15V Voltage supply | NC | U |
| | _ | -15V, max. 25mA | SYN_A 0V | V |
| <u>P</u> | | NC Not assigned | - | $\overline{}$ |
| S | Output | 0V Reference potential | - | |
| T | Output | list Actual welding current, measured on pin F; 0-10V (0V = 0A, 10V = 1000A) | | |
| U | | NC | | |
| V | Output | SYN_A 0V Synchronisation for master/slave operation | | |



5.8.2 Remote control connection socket, 19-pole

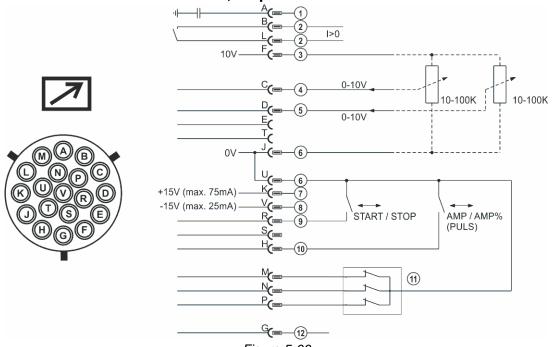


Figure 5-66

| Pos. | Pin | Signal shape | Designation | |
|------|-------|--------------|--|--|
| 1 | Α | Output | Connection for cable screen (PE) | |
| 2 | B/L | Output | Current flows signal I>0, galvanically isolated (max. +- 15V/100mA) | |
| 3 | F | Output | Reference voltage for potentiometer 10V (max. 10mA) | |
| 4 | С | Input | Control value specification for main current, 0-10V (0V = I_{min} , 10V = I_{max}) | |
| 5 | D | Input | Control value specification for secondary current, 0-10V (0V = I_{min} , 10V = I_{max}) | |
| 6 | J/U | Output | Reference 0V | |
| 7 | K | Output | Power supply +15V, max. 75mA | |
| 8 | V | Output | Power supply -15V, max. 25mA | |
| 9 | R | Input | Start/Stop welding current | |
| 10 | Н | Input | Switching between main and secondary welding currents (pulses) | |
| 11 | M/N/P | Input | Activation of control voltage specification | |
| | | | Set all 3 signals to reference potential 0V to activate external control voltage specification for main and secondary currents | |
| 12 | G | Output | Measured value I _{SETPOINT} (1V = 100A) | |

5.8.3 RINT X12 robot interface

The standard digital interface for mechanised applications (optional, retrofitting on the machine or external fitting by the customer)

Functions and signals:

- Digital inputs: start/stop, operating modes, JOB and program selection, inching, gas test
- · Analogue inputs: control voltages, e.g. for welding performance, welding current, etc.
- · Relay outputs: process signal, ready for welding, system composite fault, etc.

5.8.4 BUSINT X11 Industrial bus interface

The solution for easy integration with automated production with e.g.

- · Profinet/Profibus
- EnthernetIP/DeviceNet
- EtherCAT

etc.



5.9 PC interface

PC 300 welding parameter software

Set all welding parameters on the PC and simply transfer to one or more welding machines (accessory, set consisting of software, interface, connection leads)

- Manage up to 510 JOBs
- · Exchange JOBs with the welding machine
- · Online data communication
- · Default settings for welding data monitoring
- Always up-to-date thanks to standard update function for new welding parameters
- Data backup by easy communication between power source and PC

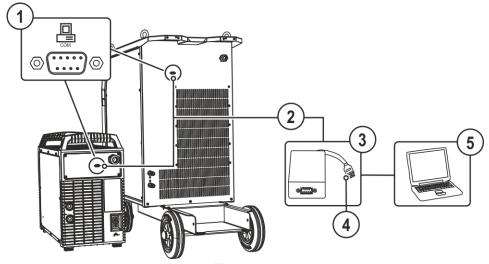


Figure 5-67

| Item | Symbol | Description |
|------|--------|--|
| 1 | COM | PC interface, serial (D-Sub connection socket, 9-pole) |
| 2 | | SECINT X10 USB |
| 3 | | USB connection |
| 4 | | Windows PC |



Equipment damage or faults may occur if the PC is connected incorrectly!

Not using the SECINT X10USB interface results in equipment damage or faults in signal transmission. The PC may be destroyed due to high frequency ignition pulses.

- Interface SECINT X10USB must be connected between the PC and the welding machine!
- The connection must only be made using the cables supplied (do not use any additional extension cables)!

5.10 Power-saving mode (Standby)

You can activate the power-saving mode by either pressing the push-button > see 4.3 chapter for a prolonged time or by setting a parameter in the machine configuration menu (time-controlled power-saving mode 55R) > see 5.12 chapter.

When power-saving mode is activated, the machine displays show the horizontal digit in the centre of the display only.

Pressing any operating element (e.g. turning a rotary knob) deactivates power-saving mode and the machine is ready for welding again.

Design and function

Access control



5.11 Access control

These accessory components can be retrofitted as an option > see 9 chapter.

To protect against unauthorised or unintentional adjustment of the welding parameters on the machine, the control input can be locked with the aid of a key switch.

Key position 1 = All parameters can be set

Key position 0 = Only the following operating elements are functional:

- "Operating mode" button
- "Welding parameter setting" rotary transducer
- "Display switching" button
- "TIG pulse welding" button
- "Select welding parameters" button
- · "Gas test" button



5.12 Machine configuration menu

Basic machine settings are defined in the machine configuration menu.

5.12.1 Selecting, changing and saving parameters

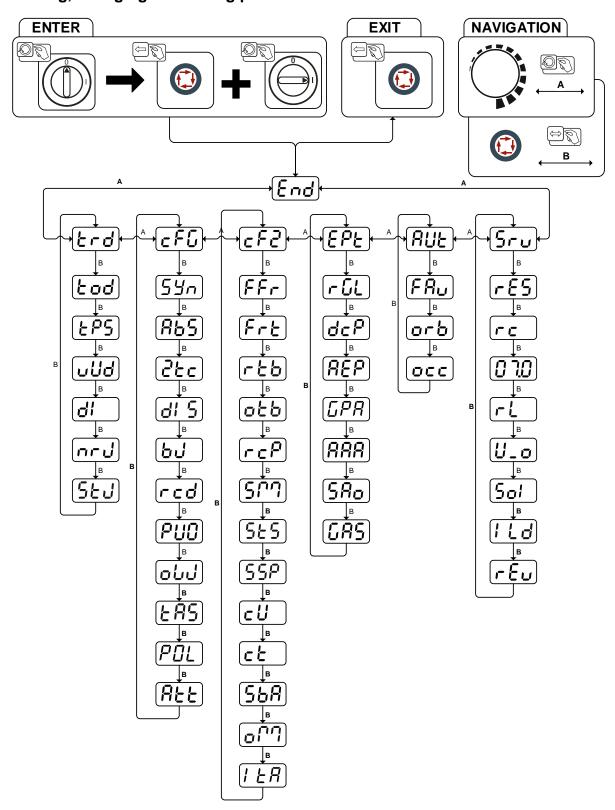


Figure 5-68

| Display | Setting/selection |
|---------|--------------------|
| End | Exit the menu Exit |



| Display | Setting/selection |
|---------------|---|
| Erd | Torch configuration menu |
| | Set welding torch functions |
| <u>Lod</u> | Torch mode (ex works 1) > see 5.7.7.2 chapter |
| FP5 | Alternative welding start – tapping start |
| | Available from torch mode 11 (welding stop by tapping remains active). |
| | Function enabled (ex works) ••FF Function disabled |
| | Up/down speed > see 5.7.7.3 chapter |
| பப்ப | Increase value > rapid current change |
| | Decrease value > slow current change |
| di | Current jump > see 5.7.7.4 chapter |
| | Current jump setting in ampere |
| חרש | Get JOB number Set maximum calcatable inha (actting: 1 to 129, factory actting 10) |
| | Set maximum selectable jobs (setting: 1 to 128, factory setting 10). Additional parameter after activating the BLOCK JOB function. |
| <u></u> | Start JOB |
| (<u>54 م</u> | Set first JOB to get (setting: 129 to 256, factory setting 129). |
| | Machine configuration |
| c F [] | Settings for machine functions and parameter display |
| | Operating principle |
| חככ | en synergic parameter setting (factory setting) |
| | <u>oFF</u> conventional parameter setting |
| [RbS] | Absolute value setting (ignition, secondary, end and hot start |
| ردور | current) > see 5.2.2 chapter |
| | □ Welding current setting, absolute □ FF Welding current setting, as a percentage of the main current (ex works) |
| | Non-latched operation (version C) > see 5.3.11.6 chapter |
| [2 E c] | Function enabled |
| | □FF Function disabled (ex works) |
| | Setting for the primary setpoint value display |
| di 5 | Defines the priority display for setpoint values: |
| | ы dpanel thickness |
| | ualwelding voltage (factory setting) |
| БJ | RINT X12, JOB control for automation solutions |
| رانان | <u></u> |
| | <u>oFF</u> off (factory setting) |
| ردط | Current display switching (MMA) |
| , <u>L D</u> | DFF Actual value display (ex works) |
| | Pulsed welding in the upslope and downslope phases > see 5.3.12 chapter |
| וטטץ | Function enabled (ex works) |
| | □FF Function disabled |
| | Filler wire welding, operating mode ² |
| لامام | [בּים] Filler wire operation for automated applications, |
| | wire is fed when current flows |
| | ☐ Representation and the second seco |
| | 3 Grant Strate |
| | TIG antistick > see 5.3.13 chapter |
| (E H 5 | function active (factory setting). |
| | <u>off</u> function inactive. |
| | · |





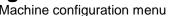


| Display | Setting/selection |
|----------------|--|
| POL | Program 0 block With machines with access block, program 0 can be disabled. When the access block has been enabled, programs 1–x only can be switched. |
| | oFFAll programs can be selected (ex works) onPrograms 1−x can be selected (program 0 disabled) |
| | Show warnings > see 7.2 chapter |
| REE | FFFFunction disabled (ex works) |
| | enFunction enabled |
| | Machine configuration (second part) |
| <u> </u> | Settings for machine functions and parameter display |
| FFr | RTF start ramp > see 5.7.6.1 chapter Welding current rises to the specified main current level in a ramp function (ex works) Welding current immediately jumps to the specified main current level |
| | RTF response > see 5.7.6.2 chapter |
| FrE | LinLinear response |
| | LaLLogarithmic responsive (ex works) |
| rest | Tungsten balling with RT AC remote control ¹ •FFFunction disabled |
| | [an]Function enabled (in addition, the "AC balance" rotary knob at the RT AC |
| | remote control has to be turned to the left stop) (ex works) |
| oŁb | Tungsten balling (old variant) |
| | Function enabled |
| | Wolding overset polarity ovitables s |
| r <u>c</u> P | Welding current polarity switching ¹ polarity switching at the RT PWS 1 19POL remote control (ex works) |
| | EFF polarity switching at the welding machine control |
| | spotmatic operating mode > see 5.3.11.5 chapter |
| ני יב | Ignition by contact with the workpiece |
| | Function enabled (ex works) Function disabled |
| | Spot time setting > see 5.3.11.5 chapter |
| [5 <i>E</i> 5] | Spot time setting > see 5.3.77.3 chapter Short spot time, setting range 5 ms to 999 ms, increments of 1 ms (ex works) |
| | FFLong spot time, setting range 0.01 s to 20.0 s, increments of 10 ms (ex works) |
| 55 <i>P</i> | Process activation setting > see 5.3.11.5 chapter |
| <u> </u> | Separate process activation (ex works) |
| | Torch cooling mode |
| [כ [] | िमिर्मAutomatic operation (ex works) |
| | Permanently enabled |
| | FFPermanently disabled |
| [c Ł | Welding torch cooling, post-flow time |
| | Setting 1–60 min. (ex works 5 min.) |
| (5 <i>6R</i>) | Time-based power-saving mode > see 5.10 chapter Time to activation of the power-saving mode in case of inactivity. |
| | Setting <u>GFF</u> = disabled or numerical value 5– 60 min. (ex works: 20). |
| | Operating mode switching via interface for automated welding |
| | ZENon-latched |
| | 215Special non-latched |
| ! ŁR | Re-ignition after arc interruption > see 5.3.10.3 chapter [FF]Function disabled or numerical value 0.1 s–5.0 s (ex works: 3 s). |



| Display | Setting/selection |
|-----------------|--|
| EPŁ | Expert menu |
| rGL | AC average value controller ¹ Delian Function enabled (ex works) DEFF Function disabled |
| dc P | Welding current polarity switch (dc+) with TIG DC Dn Polarity switch released DFF Polarity switch blocked; protects the tungsten electrode from being permanently damaged (ex works). |
| REP | Reconditioning pulse (tungsten ball stability) Cleaning effect of the tungsten ball at the end of welding. Function enabled (ex works) Function disabled |
| CPA | Automatic gas post-flow function on (factory setting) function off |
| RRR | activArc voltage measuring Function enabled (ex works) FF Function disabled |
| SR ₀ | Error output to interface for automated welding, contact SYN_A ©FF AC synchronisation or hot wire (ex works) F5n Error signal, negative logic F5P Error signal, positive logic Puc AVC (Arc voltage control) connection |
| <i>GRS</i> | Gas monitoring Depending on where the gas sensor is situated, the use of a pilot static tube and the welding process monitoring phase. □FF Function disabled (ex works). □ Monitoring during the welding process. Gas sensor between gas valve and welding torch (with pilot static tube). □ Monitoring prior to the welding process. Gas sensor between gas valve and welding torch (without pilot static tube). □ Permanent monitoring Gas sensor between gas cylinder and gas valve (with pilot static tube). |
| RUL | Automation menu ³ |
| FAu | Fast take-over of control voltage (automation) ³ Description: Figure 1: Fast take-over of control voltage (automation) ³ Description: Figure 2: Fast take-over of control voltage (automation) ³ Description: Figure 3: Fast take-over of control voltage (automation) ³ Description: Figure 3: Fast take-over of control voltage (automation) ³ Description: Figure 3: Fast take-over of control voltage (automation) ³ Description: Figure 3: Fast take-over of control voltage (automation) ³ Description: Figure 4: Fast take-over of control voltage (automation) ³ Description: Figure 4: Fast take-over of control voltage (automation) ³ Description: Figure 4: Fast take-over of control voltage (automation) ³ Description: Figure 4: Fast take-over of control voltage (automation) ³ Description: Figure 4: Fast take-over of control voltage (automation) ³ Description: Figure 5: Fast take-over of control voltage (automation) ³ Description: Figure 5: Fast take-over of control voltage (automation) ³ Description: Figure 5: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figure 6: Fast take-over of control voltage (automation) ³ Description: Figu |
| orb | Orbital welding ³ OFF Function disabled (ex works) OFF Function enabled |
| ٥٥٥ | Orbital welding ³ Correction value for orbital current |
| 5-0 | Service menu Any changes to the service menu should be agreed with the authorised service personnel. |
| r E S | Reset (to factory setting) FF: Disabled (ex works) FE: Reset the values in the machine configuration menu PL: Complete reset of all values and settings Resetting is performed when exiting the menu (End). |







| Display | Setting/selection |
|--------------|---|
| [c.c.] | Automated/Manual (rC on/off) operating mode ³ |
| | Select machine/function control |
| | enwith external control voltages/signals |
| | <u>oFF</u> with machine control |
| חרח | Software version query (example) |
| | 07.=system bus ID |
| <u>ח</u> _ כ | 03c0=version number |
| 3c 0 | System bus ID and version number are separated by a dot. |
| rL | Cable resistance alignment > see 5.12.2 chapter |
| <u>U_o</u> | Only qualified service personnel may change the parameters! |
| | TIG HF start (soft/hard) switching |
| נים כ | soft ignition (factory setting). |
| | offhard ignition. |
| | Ignition pulse limit |
| U L D | Setting 0 ms-15 ms (increments of 1 ms) |
| rEu | PCB state – qualified service personnel only! |

for AC welding machines only.
 For machines with filler wire (AW) only.
 for components for automated welding (RC) only.



5.12.2 Aligning the cable resistance

To ensure optimum welding properties, the electric cable resistance should be aligned again whenever an accessory component such as the welding torch or the intermediate hose package (AW) has been changed. The resistance value of the cables can be set directly or can be aligned by the power source. In the delivery state the cable resistance is set to the optimum values. To optimise the welding properties for other cable lengths, an alignment process (voltage correction) is necessary.

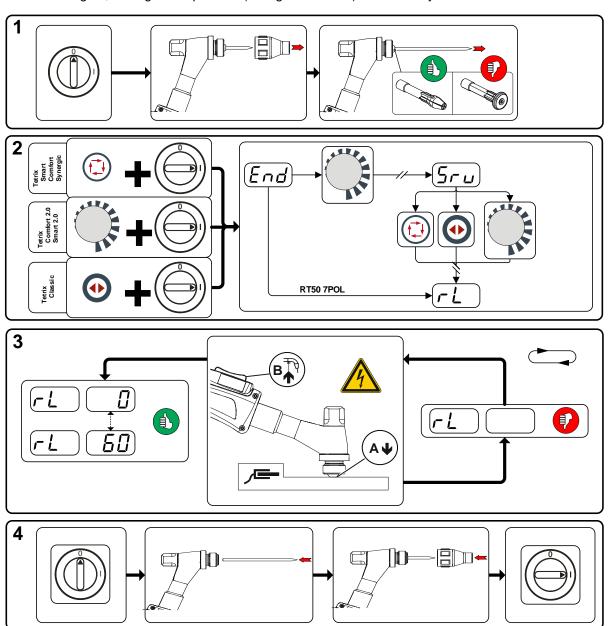


Figure 5-69

Design and function





1 Preparation

- Switch off the welding machine.
- Unscrew the gas nozzle from the welding torch.
- · Unfasten the tungsten electrode and extract.

2 Configuration

- Press the or (Tetrix Classic) push-button while simultaneously switching on the welding machine.
- · Release push-button.
- The required parameter can now be selected using the rotary knob.

3 Adjustment/measurement

• Applying slight pressure, press the welding torch with the collet against a clean, purged location on the workpiece and then press the torch trigger for approx. 2 seconds. A short-circuit current will flow briefly, which is used to determine and display the cable resistance. The value can be between 0 m Ω and 60 m Ω . The new value is immediately saved without requiring further confirmation. If no value is shown on the right-hand display, then measurement failed. The measurement must be repeated.

4 Restoring welding standby mode

- · Switch off the welding machine.
- Lock the tungsten electrode in the collet again.
- Screw the gas nozzle onto the welding torch.
- · Switch on the welding machine



6 Maintenance, care and disposal

6.1 General

▲ DANGER



Risk of injury due to electrical voltage after switching off! Working on an open machine can lead to fatal injuries! Capacitors are loaded with electrical voltage during operation. Voltage remains present for up to four minutes after the mains plug is removed.

- 1. Switch off machine.
- 2. Remove the mains plug.
- 3. Wait for at last 4 minutes until the capacitors have discharged!

▲ WARNING



Incorrect maintenance, testing and repair!

Maintenance, testing and repair of the machine may only be carried out by skilled and qualified personnel. A qualified person is one who, because of his or her training. knowledge and experience, is able to recognise the dangers that can occur while testing welding power sources as well as possible subsequent damage, and who is able to implement the required safety procedures.

Observe the maintenance instructions > see 6.3 chapter.

In the event that the provisions of one of the below-stated tests are not met, the machine must not be operated again until it has been repaired and a new test has been carried out!

Repair and maintenance work may only be performed by qualified authorised personnel; otherwise the right to claim under warranty is void. In all service matters, always consult the dealer who supplied the machine. Return deliveries of defective equipment subject to warranty may only be made through your dealer. When replacing parts, use only original spare parts. When ordering spare parts, please quote the machine type, serial number and item number of the machine, as well as the type designation and item number of the spare part.

Under the specified ambient conditions and normal working conditions this machine is essentially maintenance-free and requires just a minimum of care.

Contamination of the machine may impair service life and duty cycle. The cleaning intervals depend on the ambient conditions and the resulting contamination of the machine. The minimum interval is every six months.

6.2 Cleaning

- Clean the outer surfaces with a moist cloth (no aggressive cleaning agents).
- Purge the machine venting channel and cooling fins (if present) with oil- and water-free compressed air. Compressed air may overspeed and destroy the machine fans. Never direct the compressed air directly at the machine fans. Mechanically block the fans, if required.
- Check the coolant for contaminants and replace, if necessary.

6.2.1 Dirt filter

The duty cycle of the welding machine decreases as an effect of the reduced cooling air volume. Depending on the amount of dirt building up (at least every two months), the dirt filter has to be uninstalled and cleaned regularly (e.g. by purging with compressed air).

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6.3 Maintenance work, intervals

6.3.1 Daily maintenance tasks

Visual inspection

- · Mains supply lead and its strain relief
- · Gas cylinder securing elements
- Check hose package and power connections for exterior damage and replace or have repaired by specialist staff as necessary!
- · Gas tubes and their switching equipment (solenoid valve)
- Check that all connections and wearing parts are hand-tight and tighten if necessary.
- · Check correct mounting of the wire spool.
- Wheels and their securing elements
- Transport elements (strap, lifting lugs, handle)
- Other, general condition

Functional test

- Operating, message, safety and adjustment devices (Functional test)
- · Welding current cables (check that they are fitted correctly and secured)
- Gas tubes and their switching equipment (solenoid valve)
- · Gas cylinder securing elements
- Check correct mounting of the wire spool.
- Check that all screw and plug connections and replaceable parts are secured correctly, tighten if necessary.
- · Remove any spatter.
- Clean the wire feed rollers on a regular basis (depending on the degree of soiling).

6.3.2 Monthly maintenance tasks

Visual inspection

- · Casing damage (front, rear and side walls)
- · Wheels and their securing elements
- Transport elements (strap, lifting lugs, handle)
- Check coolant tubes and their connections for impurities

Functional test

- Selector switches, command devices, emergency stop devices, voltage reducing devices, message and control lamps
- Check that the wire guide elements (inlet nipple, wire guide tube) are fitted securely.
- · Check coolant tubes and their connections for impurities
- Check and clean the welding torch. Deposits in the torch can cause short circuits and have a negative impact on the welding result, ultimately causing damage to the torch.

6.3.3 Annual test (inspection and testing during operation)

A periodic test according to IEC 60974-4 "Periodic inspection and test" has to be carried out. In addition to the regulations on testing given here, the relevant local laws and regulations must also be observed.

For more information refer to the "Warranty registration" brochure supplied and our information regarding warranty, maintenance and testing at www.ewm-group.com!

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Maintenance, care and disposal

Disposing of equipment



6.4 Disposing of equipment



Proper disposal!

The machine contains valuable raw materials, which should be recycled, and electronic components, which must be disposed of.



- Do not dispose of in household waste!
- Observe the local regulations regarding disposal!
- According to European provisions (Directive 2012/19/EU on Waste of Electrical and Electronic
 Equipment), used electric and electronic equipment may no longer be placed in unsorted municipal
 waste. It must be collected separately. The symbol depicting a waste container on wheels indicates
 that the equipment must be collected separately.
 - This machine has to be disposed of, or recycled, in accordance with the waste separation systems in use.
- According to German law (law governing the distribution, taking back and environmentally correct disposal of electric and electronic equipment (ElektroG)), used machines are to be placed in a collection system separate from unsorted municipal waste. The public waste management utilities (communities) have created collection points at which used equipment from private households can be disposed of free of charge.
- Information about returning used equipment or about collections can be obtained from the respective municipal administration office.
- In addition to this, returns are also possible throughout Europe via EWM sales partners.

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7 Rectifying faults

All products are subject to rigorous production checks and final checks. If, despite this, something fails to work at any time, please check the product using the following flowchart. If none of the fault rectification procedures described leads to the correct functioning of the product, please inform your authorised dealer.

7.1 Checklist for rectifying faults



The correct machine equipment for the material and process gas in use is a fundamental requirement for perfect operation!

| Legend | Symbol | Description |
|--------|--------|-------------|
| | * | Fault/Cause |
| | * | Remedy |

Mains fuse triggers

- ✓ Unsuitable mains fuse
 - Set up recommended mains fuse > see 8 chapter.

Functional errors

- Insufficient coolant flow
 - Check coolant level and refill if necessary
 - ★ Eliminate kinks in conduit system (hose packages)
 - Reset automatic cutout of the coolant pump by activating
- Air in the coolant circuit
 - ★ Vent coolant circuit > see 7.6 chapter
- ✓ Several parameters cannot be set (machines with access block)
 - ★ Entry level is blocked, disable access lock > see 5.11 chapter
- ✓ No machine control signal light is illuminated after switching on
- ✓ No welding power
 - ★ Phase failure > check mains connection (fuses)
- ✓ Connection problems
 - Make control lead connections and check that they are fitted correctly.

Welding torch overheated

- ✓ Loose welding current connections
 - ★ Tighten power connections on the torch and/or on the workpiece
 - ★ Tighten contact tip correctly
- ✓ Overload
 - Check and correct welding current setting
 - ★ Use a more powerful welding torch

No arc ignition

- Incorrect ignition type setting.
 - Ignition type: Select "HF start". Depending on the machine, the setting is defined by the changeover switch for ignition types or the F parameter in one of the machine menus (see the "Control operating instructions", if applicable).

Bad arc ignition

- ✓ Material inclusions in the tungsten electrode due to contact with filler material or workpiece
 - Regrind or replace the tungsten electrode
- ✓ Bad current transfer on ignition
 - Check the setting on the "Tungsten electrode diameter/Ignition optimisation" rotary dial and increase if necessary (higher ignition energy).



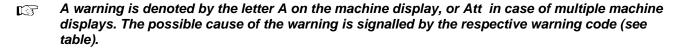
Unstable arc

- ✓ Material inclusions in the tungsten electrode due to contact with filler material or workpiece
 - Regrind or replace the tungsten electrode
- ✓ Incompatible parameter settings
 - Check settings and correct if necessary

Pore formation

- ✓ Inadequate or missing gas shielding.
 - * Check shielding gas setting and replace shielding gas cylinder if necessary
 - Shield welding site with protective screens (draughts affect the welding result)
 - ★ Use gas lens for aluminium applications and high-alloy steels
- Unsuitable or worn welding torch equipment
 - ★ Check size of gas nozzle and replace if necessary
- ✓ Condensation (hydrogen) in the gas tube
 - ★ Purge hose package with gas or replace

7.2 Warnings



The display of possible warning numbers depends on the machine version (interfaces/functions).

- In case of multiple warnings, these are displayed in sequence.
- Document machine warning and inform service personnel, if required.

| Warning code | Possible cause | Remedy |
|--------------|--|---|
| 1 | Machine excess temperature | Allow the machine to cool down |
| | | |
| 2 | Half-wave failures | Check process parameters |
| 3 | Welding torch cooling warning | Check coolant level and refill if necessary |
| 4 | Gas warning | Check gas supply |
| 5 | See warning number 3 | - |
| 6 | Welding consumable (wire electrode) fault | Check wire feeding (with machines with filler wire) |
| 7 | CAN bus failure | Inform service |
| 32 | Encoder malfunction, drive | Inform service |
| 33 | Drive is operating under overload conditions | Adjust mechanical load |
| 34 | JOB unknown | Select alternative JOB |

The warnings can be reset by pressing a push-button (see table):

| Welding machine control | Smart | Classic | Comfort | Smart 2 Comfort 2 | Synergic |
|-------------------------|----------|---------|--------------------|----------------------|---------------|
| Push-button | © | • | • AMP • VOLT • JOB | kw V | VOLT JOB PROG |

Rectifying faults

Error messages



7.3 Error messages

A welding machine error is indicated by an error code being displayed (see table) on the display on the machine control.

In the event of a machine error, the power unit is shut down.

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The display of possible error numbers depends on the machine version (interfaces/functions).

- If multiple errors occur, these are displayed in succession.
- · Document machine errors and inform service staff as necessary.

| Error message | Possible cause | Remedy |
|---------------|--|---|
| Err 3 | Tacho error | Check wire guide/hose package |
| | Wire feeder is not connected | Switch off cold wire mode in the machine configuration menu (off status) Connect the wire feeder |
| Err 4 | Temperature error | Allow the machine to cool down |
| | Error in emergency stop circuit (interface for automated welding) | Check the external interrupt equipmentCheck jumper JP 1 on PCB T320/1 |
| Err 5 | Overvoltage | Switch off machine and check the mains |
| Err 6 | Low voltage | voltage |
| Err 7 | Coolant error (with connected cooling unit only) | Check coolant level and refill if necessary |
| Err 8 | Gas error | Check gas supply |
| Err 9 | Secondary overvoltage | Switch the machine off and on again. |
| Err 10 | PE error | If the error persists, contact service. |
| Err 11 | FastStop position | Acknowledge error via robot interface (if available) |
| Err 12 | VRD error | Switch the machine off and on again. If the error persists, contact service. |
| Err 16 | Pilot arc current | Check welding torch |
| Err 17 | Filler wire error Excess current or deviation of nominal/actual wire value | Check wire feed mechanism (drive, hose packages, torch, process wire feed speed and robot movement speed) and adjust, if required |
| Err 18 | Plasma gas error Nominal value specification differs considerably from the actual value. | Check plasma gas supply (tightness, kinks, guide, connections, closure) |
| Err 19 | Shielding gas error Nominal value specification differs considerably from the actual value | Check plasma gas supply (tightness, kinks, guide, connections, closure) |
| Err 20 | Coolant flow Coolant flow volume too low | Check cooling circuit (coolant level, tightness, kinks, guide, connections, closure) |
| Err 22 | Cooling circuit excess temperature | Check cooling circuit (coolant level, nominal temperature value) |
| Err 23 | HF choke excess temperature | Allow the machine to cool down Adjust processing cycle times if necessary |
| Err 24 | Pilot arc ignition error | Check plasma torch consumables |
| Err 32 | Electronics error (I>0 error) | |
| Err 33 | Electronics error (Uact error) | |
| Err 34 | Electronics error (A/D channel error) | Switch the machine off and on again. |
| Err 35 | Electronics error (edge error) | If the error persists, contact service. |
| Err 36 | Electronics error (S-Sign) | |
| Err 37 | Electronics error (temperature error) | Allow the machine to cool down. |



| Error message | Possible cause | Remedy |
|---------------|---|--|
| Err 38 | | Custoh the machine off and an again |
| Err 39 | Electronics error (secondary overvoltage) | Switch the machine off and on again. If the error persists, contact service. |
| Err 40 | Electronics error (I>0 error) | Inform service |
| Err 48 | Ignition error | Check welding process |
| Err 49 | Arc interruption | Inform service |
| Err 51 | Error in emergency stop circuit (interface for automated welding) | Check the external interrupt equipmentCheck jumper JP 1 on PCB T320/1 |
| Err 57 | Auxiliary drive error, tacho error | Check the auxiliary drive (tacho – no signal, M3.51 defective > inform service) |
| Err 59 | Incompatible component | Replace component |

7.4 Resetting welding parameters to the factory settings

All customised welding parameters that are stored will be replaced by the factory settings.

To reset the welding parameters or machine settings to the factory settings, select parameter FES in the service menu FE > see 5.12 chapter.

7.5 Display machine control software version

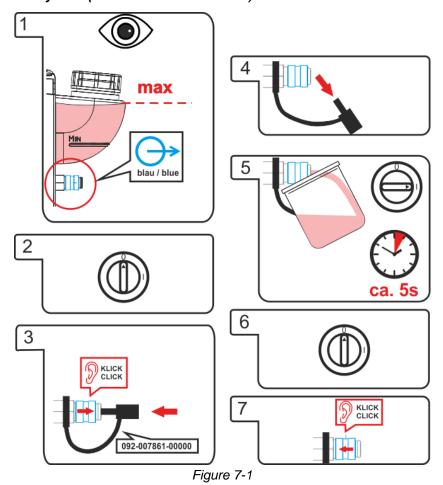
The query of the software versions only serves to inform the authorised service staff. It is available in the machine configuration menu > see 5.12 chapter.





7.6 Vent coolant circuit

- Coolant tank and quick connect coupling of coolant supply and return are only fitted in machines with water cooling.
- To vent the cooling system always use the blue coolant connection, which is located as deep as rigan (possible inside the system (close to the coolant tank)!





8 Technical data

Performance specifications and guarantee only in connection with original spare and replacement parts!

8.1 Tetrix 351 FW

| | TIG | MMA |
|--|---|---------------------------|
| Welding current | 5 A-350 A | |
| Welding voltage | 10.2 V–24.0 V 20.2 V–34.0 V | |
| Duty cycle at 40 °C | 350 A (10 | 00% DC) |
| Load cycle | 10 min. (60% DC ≙ 6 mir | n. welding, 4 min. pause) |
| Open circuit voltage | 79 | V |
| Mains voltage (tolerances) | 3 x 400 V (–2 | 5% to +20%) |
| Frequency | 50/6 | 0 Hz |
| Mains fuse (safety fuse, slow-blow) | 3 x 16 A | 3 x 25 A |
| Mains connection lead | H07RN | I-F4G6 |
| Max. connected load | 10.9 kVA | 15.4 kVA |
| Recommended generator rating | 20.8 | kVA |
| cosφ/efficiency | 0.99 (90%) | |
| Insulation class/protection classification | H/IP 23 | |
| Ambient temperature | −25 °C to +40 °C ¹ | |
| Machine cooling/torch cooling | Fan/gas or water | |
| Noise level | < 70 dB(A) | |
| Cooling capacity at 1 l/min. | 1500 W | |
| Max. flow rate | 5 l/n | nin. |
| Coolant outlet pressure | Max. 3 | .5 bar |
| Max. tank capacity | 12 | • |
| Workpiece lead | 70 r | nm² |
| Dimensions L/W/H | 1085 mm x 450 | |
| | 42.7 inch x 17.7 | |
| Weight | 131 kg 289 lb | |
| EMC class | | · · · |
| | A [H[/S]/ C€ | |
| Safety identification | · | |
| Harmonised standards used | see declaration of conformity (machine documentation) | |

¹ Ambient temperature dependent on coolant! Observe the coolant temperature range of the torch cooling



8.2 Tetrix 401 FW

| | TIG | MMA |
|--|---|---------------------------|
| Welding current | 5 A-400 A | |
| Welding voltage | 10.2 V–26.0 V | 20.2 V-36.0 V |
| Duty cycle at 40 °C | 400 A (1 | 00% DC) |
| Load cycle | 10 min. (60% DC ≙ 6 min | n. welding, 4 min. pause) |
| Open circuit voltage | 79 |) V |
| Mains voltage (tolerances) | 3 x 400 V (–2 | 25% to +20%) |
| Frequency | 50/6 | 0 Hz |
| Mains fuse (safety fuse, slow-blow) | 3 x 20 A | 3 x 32 A |
| Mains connection lead | H07RN | N-F4G6 |
| Max. connected load | 13.5 kVA | 18.5 kVA |
| Recommended generator rating | 25.0 kVA | |
| cosφ/efficiency | 0.99 (90%) | |
| Insulation class/protection classification | H/IP 23 | |
| Ambient temperature | −25 °C to +40 °C ¹ | |
| Machine cooling/torch cooling | Fan/gas or water | |
| Noise level | < 70 dB(A) | |
| Cooling capacity at 1 l/min. | 1500 W | |
| Max. flow rate | 5 l/min. | |
| Coolant outlet pressure | Max. | 3.5 bar |
| Max. tank capacity | | 21 |
| Workpiece lead | 70 ו | mm ² |
| Dimensions L/W/H | 1085 mm x 450 mm x 1003 mm 42.7 inch x 17.7 inch x 39.5 inch | |
| Weight | 131 kg 289 lb | |
| EMC class | | 4 |
| Safety identification | HI / S / C € | |
| Harmonised standards used | see declaration of conformity (machine documentation) | |

¹ Ambient temperature dependent on coolant! Observe the coolant temperature range of the torch cooling



8.3 Tetrix 451 FW

| | TIG | MMA |
|--|---|---------------------------|
| Welding current | 5 A-450 A | |
| Welding voltage | 10.2 V-28.0 V | 20.2 V-38.0 V |
| Duty cycle at 40 °C | 450 A (8 | • |
| | 420 A (10 | |
| Load cycle | 10 min. (60% DC △ 6 mir | n. welding, 4 min. pause) |
| Open circuit voltage | 79 | V |
| Mains voltage (tolerances) | 3 x 400 V (–2 | 5% to +20%) |
| Frequency | 50/6 | 0 Hz |
| Mains fuse (safety fuse, slow-blow) | 3 x 25 A | 3 x 32 A |
| Mains connection lead | H07RN | I-F4G6 |
| Max. connected load | 16.3 kVA | 22.0 kVA |
| Recommended generator rating | 29.7 kVA | |
| cosφ/efficiency | 0.99 (90%) | |
| Insulation class/protection classification | H/IP 23 | |
| Ambient temperature | –25 °C to +40 °C ¹ | |
| Machine/torch cooling | Fan/gas or water | |
| Noise level | < 70 dB(A) | |
| Cooling capacity at 1 l/min. | 1500 W | |
| Max. flow rate | 5 l/min. | |
| Coolant outlet pressure | Max. 3 | .5 bar |
| Max. tank capacity | 12 | |
| Workpiece lead | 70 mm ² | |
| Dimensions L/W/H | 1085 mm x 450 mm x 1003 mm | |
| | 42.7 inch x 17.7 inch x 39.5 inch | |
| Weight | 131 kg | |
| | 289 lb | |
| EMC class | A | |
| Safety identification | IN / S / C € | |
| Harmonised standards used | see declaration of conformity (machine documentation) | |

¹ Ambient temperature dependent on coolant! Observe the coolant temperature range of the torch cooling



8.4 Tetrix 551 FW

| | TIG | MMA |
|--|---|---------------------------|
| Welding current | 5 A-550 A | |
| Welding voltage | 10.2 V-32.0 V | 20.2 V-42.0 V |
| Duty cycle at 40 °C | 550 A (60% DC) 420 A (100% DC) | |
| Load cycle | , | n. welding, 4 min. pause) |
| Open circuit voltage | 79 | V |
| Mains voltage (tolerances) | 3 x 400 V (–2 | 5% to +20%) |
| Frequency | 50/6 | 0 Hz |
| Mains fuse (safety fuse, slow-blow) | 3 x 25 A | 3 x 32 A |
| Mains connection lead | H07RN | I-F4G6 |
| Max. connected load | 22.6 kVA | 29.5 kVA |
| Recommended generator rating | 39.8 kVA | |
| cosφ/efficiency | 0.99 (90%) | |
| Insulation class/protection classification | H/IP 23 | |
| Ambient temperature | −25 °C to +40 °C ¹ | |
| Machine cooling/torch cooling | Fan/gas or water | |
| Noise level | < 70 dB(A) | |
| Cooling capacity at 1 l/min. | 1500 W | |
| Max. flow rate | 5 l/min. | |
| Coolant outlet pressure | Max. 3 | .5 bar |
| Max. tank capacity | 12 | |
| Workpiece lead | 95 mm ² | |
| Dimensions L/W/H | 1085 mm x 450 mm x 1003 mm 42.7 inch x 17.7 inch x 39.5 inch | |
| Weight | 131 kg 289 lb | |
| EMC class | A | 4 |
| Constructed to standard | EH[/S/C€ | |
| Harmonised standards used | see declaration of conformity (machine documentation) | |

¹ Ambient temperature dependent on coolant! Observe the coolant temperature range of the torch cooling



9 Accessories

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Performance-dependent accessories like torches, workpiece leads, electrode holders or intermediate hose packages are available from your authorised dealer.

9.1 Remote controls and accessories

| Туре | Designation | Item no. |
|--------------------|--|------------------|
| RTF1 19POL 5 M | Foot-operated remote control current with connection cable | 094-006680-00000 |
| RT1 19POL | Remote control current | 090-008097-00000 |
| RTG1 19POL 5m | Remote control, current | 090-008106-00000 |
| RTG1 19POL 10m | Remote control, current | 090-008106-00010 |
| RTP1 19POL | Remote control spot welding / pulses | 090-008098-00000 |
| RTP2 19POL | Remote control spot welding / pulses | 090-008099-00000 |
| RTP3 spotArc 19POL | spotArc remote control for spot welding / pulses | 090-008211-00000 |
| RT50 7POL | Remote control, full functionality | 090-008793-00000 |
| RA5 19POL 5M | Remote control e.g. connection cable | 092-001470-00005 |
| RA10 19POL 10M | Remote control e.g. connection cable | 092-001470-00010 |
| RA20 19POL 20M | Remote control e.g. connection cable | 092-001470-00020 |
| RV5M19 19POLE 5M | Extension cable | 092-000857-00000 |

9.2 Welding torch cooling system

| Туре | Designation | Item no. |
|-----------------|------------------------------|------------------|
| KF 23E-10 | Coolant (-10 °C), 9.3 I | 094-000530-00000 |
| KF 23E-200 | Coolant (-10 °C), 200 litres | 094-000530-00001 |
| KF 37E-10 | Coolant (-20 °C), 9.3 I | 094-006256-00000 |
| KF 37E-200 | Coolant (-20 °C), 200 I | 094-006256-00001 |
| TYP 1 | Frost protection tester | 094-014499-00000 |
| HOSE BRIDGE UNI | Tube bridge | 092-007843-00000 |

9.3 Options

| Туре | Designation | Item no. |
|--|---|------------------|
| ON 7pol | Optional 7-pole retrofit connection socket Accessory components and digital interfaces | 092-001826-00000 |
| ON 19pol 351/451/551 | Optional 19-pole retrofit connection socket Accessory components and analogue A interface | 092-001951-00000 |
| ON 12pol Retox Tetrix 300/400/401/351/451/551 | Optional 12-pole retrofit connection socket | 092-001807-00000 |
| ON Filter T/P | Retrofit option contamination filter for air inlet | 092-002092-00000 |
| ON LB Wheels 160x40MM | Retrofit option for locking brake for machine wheels | 092-002110-00000 |
| ON Key Switch | Optional retrofit kit for key switch | 092-001828-00000 |
| ON Tool Box | Retrofit option tool box | 092-002138-00000 |
| ON HS XX1 | Mount for hose packages and remote control | 092-002910-00000 |
| ON Holder Gas Bottle <50L | Holding plate for gas cylinders smaller than 50 litres | 092-002151-00000 |
| ON Shock Protect | Ram protection retrofit option | 092-002154-00000 |

9.4 General accessories

| Туре | Designation | Item no. |
|----------------------------|-----------------------------------|------------------|
| DM 842 Ar/CO2 230bar 30l D | Pressure regulator with manometer | 394-002910-00030 |
| GH 2X1/4" 2M | Gas hose | 094-000010-00001 |
| 32A 5POLE/CEE | Machine plug | 094-000207-00000 |
| ADAP 8-5 POL | 8 to 5-pole adapter | 092-000940-00000 |







9.5 Computer communication

| Туре | Designation | Item no. |
|-----------|--|------------------|
| PC300.Net | PC300.Net welding parameter software kit incl. | 090-008777-00000 |
| | cable and SECINT X10 USB interface | |



Appendix A 10

10.1 JOB-List

| | L | Process Material | | | | | Wire | | | | | Seam position | | | | |
|------------------|-------------------------|------------------|-------------------------|-----|-------|-----|-------------------------|------------|-------------------------|-----|-------------------------|---------------|-----------------------|--------------------|----------------------|--|
| | | TIG hot wire | TIG cold wire | | | | | Ø | | | Fillet weld | Butt joint | Fillet weld lap joint | Vertical-down weld | Tungsten electrode Ø | |
| JOB | 1IG | TIG h | TIG CO | MMA | | 9,0 | 8,0 | 1,0 | 1,2 | 1,6 | | • | ~ | | ø → - | |
| 1 | Re | ser | ved | | | | | | | | | | | | | |
| 2 | ☑ | | | | CrNi | | | | | | V | | | | 1 | |
| 3 | ☑ | | | | CrNi | | | | | | V | | | | 1.6 | |
| 4 5 6 7 | ☑ | | | | CrNi | | | | | | V | | | | 2 | |
| 5 | \square | | V | | CrNi | | \square | | | | V | | | | 2.4 | |
| 6 | \square | | $\overline{\mathbf{V}}$ | | CrNi | | V | led | $\mathbf{\Sigma}$ | | $\overline{\mathbf{V}}$ | | | | 3.2 | |
| | | | Ŋ | | CrNi | | V | lacksquare | $\overline{\mathbf{V}}$ | | $\overline{\mathbf{N}}$ | | | | >3.2 | |
| 8 | \square | | | | CrNi | | | | | | | V | | | 1 | |
| 9 | | | | | CrNi | | | | | | | V | | | 1.6 | |
| 10 | | | | | CrNi | | | | | | | V | | | 2 | |
| 11 | | | V | | CrNi | | Ø | V | ✓ | | | V | | | 2.4 | |
| 12 | \square | | V | | CrNi | | V | V | \checkmark | | | V | | | 3.2 | |
| 13 | \square | | V | | CrNi | | Ø | | | | | \checkmark | | | >3.2 | |
| 14 | | | | | CrNi | | | | | | | | V | | 1 | |
| 15 | \square | | | | CrNi | | | | | | | | V | | 1.6 | |
| 16 | \square | | | | CrNi | | | | | | | | V | | 2 | |
| 17 | \square | | V | | CrNi | | $\overline{\mathbf{Q}}$ | V | V | | | | V | | 2.4 | |
| 18 | \square | | V | | CrNi | | Ø | Ø | V | | | | V | | 3.2 | |
| 19 | \square | | V | | CrNi | | Ø | Ø | V | | | | V | | >3.2 | |
| 20 | \square | | | | CrNi | | | | | | | | | \square | 1 | |
| 21 | $\overline{\mathbf{A}}$ | | | | CrNi | | | | | | | | | V | 1.6 | |
| 22 | \square | | | | CrNi | | | | | | | | | \square | 2 | |
| 23 | \square | | V | | CrNi | | V | V | ✓ | | | | | \square | 2.4 | |
| 24 | \square | | V | | CrNi | | V | V | V | | | | | V | 3.2 | |
| 25 | \square | | V | | CrNi | | V | V | V | | | | | V | >3.2 | |
| 26 | \square | | | | Fe/St | | | | | | V | | | | 1 | |
| 27 | \square | | | | Fe/St | | | | | | V | | | | 1.6 | |
| 28 | Ø | | | | Fe/St | Ī | | | | | V | | | | 2 | |
| 29 | ☑ | | V | | Fe/St | | V | V | V | | V | | | | 2.4 | |
| 30 | Ø | | V | | Fe/St | Ī | V | V | V | | V | | | | 3.2 | |
| 31 | \square | | V | | Fe/St | | V | V | V | | V | | | | >3.2 | |
| 32 | ☑ | | | | Fe/St | | | | | | | | | | 1 | |
| 33 | Ø | | | | Fe/St | | | | | | | V | | | 1.6 | |
| 34 | Ø | | | | Fe/St | | | | | | | V | | | 2 | |
| 35 | V | | V | | Fe/St | | Ø | V | V | | | V | | | 2.4 | |
| | | 1 | _ | 1 | | ı | | _ | _ | ı | | 1 | ı | | | |



| | Process Material | | | | | ٧ | Vire | Э | | Se | 8 | | | | |
|-----|-------------------------|--------------|---------------|-----|-------|-----|----------|-------------------------|-----|-----|-------------|-------------------------|-------------------------|-------------------------|----------------------|
| | | TIG hot wire | TIG cold wire | | | | | Ø | | | Fillet weld | Butt joint | Fillet weld lap joint | Vertical-down weld | Tungsten electrode Ø |
| JOB | TIG | TIG h | TIG C | MMA | | 9,0 | 8,0 | 1,0 | 1,2 | 1,6 | | • | ď | | ø → + |
| 36 | ☑ | | ☑ | | Fe/St | | ☑ | | | | | V | | | 3.2 |
| 37 | V | | V | | Fe/St | | ☑ | $\overline{\mathbf{V}}$ | ☑ | | | $\overline{\mathbf{A}}$ | | | >3.2 |
| 38 | V | | | | Fe/St | | | | | | | | V | | 1 |
| 39 | $\overline{\mathbf{A}}$ | | | | Fe/St | | | | | | | | $\overline{\checkmark}$ | | 1.6 |
| 40 | | | | | Fe/St | | | | | | | | V | | 2 |
| 41 | | | V | | Fe/St | | V | V | V | | | | V | | 2.4 |
| 42 | | | V | | Fe/St | | | V | V | | | | V | | 3.2 |
| 43 | | | V | | Fe/St | | V | V | V | | | | $\overline{\mathbf{A}}$ | | >3.2 |
| 44 | ☑ | | | | Fe/St | | | | | | | | | ☑ | 1 |
| 45 | | | | | Fe/St | | | | | | | | | | 1.6 |
| 46 | | | | | Fe/St | | | | | | | | | $\overline{\mathbf{V}}$ | 2 |
| 47 | ☑ | | V | | Fe/St | | V | V | V | | | | | ☑ | 2.4 |
| 48 | | | V | | Fe/St | | ✓ | V | V | | | | | $\overline{\mathbf{V}}$ | 3.2 |
| 49 | | | V | | Fe/St | | V | V | V | | | | | $\overline{\mathbf{A}}$ | >3.2 |
| 50 | | | | | Cu | | | | | | V | | | | 1 |
| 51 | | | | | Cu | | | | | | V | | | | 1.6 |
| 52 | | | | | Cu | | | | | | V | | | | 2 |
| 53 | V | | V | | Cu | | | V | | | V | | | | 2.4 |
| 54 | | | V | | Cu | | | V | | | V | | | | 3.2 |
| 55 | | | | | Cu | | | | | | V | | | | >3.2 |
| 56 | | | | | Cu | | | | | | | V | | | 1 |
| 57 | | | | | Cu | | | | | | | V | | | 1.6 |
| 58 | | | | | Cu | | | | | | | V | | | 2 |
| 59 | | | V | | Cu | | | V | | | | V | | | 2.4 |
| 60 | | | V | | Cu | | | V | | | | V | | | 3.2 |
| 61 | ☑ | | | | Cu | | | | | | | V | | | >3.2 |
| 62 | ☑ | | | | Cu | | | | | | | | $\overline{\mathbf{A}}$ | | 1 |
| 63 | V | | | | Cu | | | | | | | | V | | 1.6 |
| 64 | ☑ | | | | Cu | | | | | | | | $\overline{\mathbf{A}}$ | | 2 |
| 65 | ☑ | | V | | Cu | | | V | | | | | V | | 2.4 |
| 66 | V | | V | | Cu | | | V | | | | | V | | 3.2 |
| 67 | Ø | | | | Cu | | | | | | | | V | | >3.2 |
| 68 | V | | | | Cu | | | | | | | | | V | 1 |
| 69 | ☑ | | | | Cu | | | | | | | | | V | 1.6 |
| 70 | V | | | | Cu | | | | | | | | | V | 2 |
| 71 | ☑ | | V | | Cu | | | V | | | | | | V | 2.4 |
| 72 | V | | V | | Cu | | | V | | | | | | \square | 3.2 |
| 73 | ☑ | | | | Cu | | | | | | | | | | >3.2 |



| | F | Pro | ces | s | Material | Material Wi | | | | | Se | am p | ositio | n | 8 |
|-----|----------|--------------|---------------|-----|----------|-------------|-----|----------|-----|-----|-------------|------------|-----------------------|--------------------|----------------------|
| | | TIG hot wire | TIG cold wire | | | | | Ø | | | Fillet weld | Butt joint | Fillet weld lap joint | Vertical-down weld | Tungsten electrode Ø |
| JOB | TIG | TIG ho | TIG CC | MMA | | 9,0 | 8,0 | 1,0 | 1,2 | 1,6 | | • | ď | | Ø → ← |
| 74 | V | | | | CuZn | | | | | | V | | | | 1 |
| 75 | V | | | | CuZn | | | | | | V | | | | 1.6 |
| 76 | V | | | | CuZn | | | | | | V | | | | 2 |
| 77 | V | | V | | CuZn | | | V | | | V | | | | 2.4 |
| 78 | V | | V | | CuZn | | | V | | | V | | | | 3.2 |
| 79 | V | | | | CuZn | | | | | | V | | | | >3.2 |
| 80 | V | | | | CuZn | | | | | | | V | | | 1 |
| 81 | V | | | | CuZn | | | | | | | V | | | 1.6 |
| 82 | V | | | | CuZn | | | | | | | V | | | 2 |
| 83 | V | | V | | CuZn | | | V | | | | V | | | 2.4 |
| 84 | V | | V | | CuZn | | | V | | | | V | | | 3.2 |
| 85 | V | | | | CuZn | | | | | | | V | | | >3.2 |
| 86 | 1 | | | | CuZn | | | | | | | | V | | 1 |
| 87 | Ø | | | | CuZn | | | | | | | | V | | 1.6 |
| 88 | <u> </u> | | | | CuZn | | | | | | | | <u> </u> | | 2 |
| 89 | V | | V | | CuZn | | | ☑ | | | | | V | | 2.4 |
| 90 | <u> </u> | | ☑ | | CuZn | | | <u></u> | | | | | <u> </u> | | 3.2 |
| 91 | <u> </u> | | | | CuZn | | | | | | | | <u> </u> | | >3.2 |
| 92 | <u></u> | | | | CuZn | | | | | | | | | V | 1 |
| 93 | <u> </u> | | | | CuZn | | | | | | | | | <u></u> | 1.6 |
| 94 | <u></u> | | | | CuZn | | | | | | | | | <u> </u> | 2 |
| 95 | <u></u> | | Ø | | CuZn | | | 1 | | | | | | <u></u> ✓ | 2.4 |
| 96 | <u></u> | | <u></u> | | CuZn | | | <u> </u> | | | | | | <u></u> ✓ | 3.2 |
| 97 | <u></u> | | | | CuZn | | | | | | | | | <u></u> | >3.2 |
| 98 | <u> </u> | | | | Special | | | | | | V | | | | 1 |
| 99 | <u> </u> | | | | Special | | | | | | <u> </u> | | | | 1.6 |
| 100 | <u></u> | | | | Special | | | | | | <u> </u> | | | | 2 |
| 101 | <u>_</u> | | | | Special | | | | | | <u> </u> | | | | 2.4 |
| 102 | <u> </u> | | | | Special | | | | | | <u> </u> | | | | 3.2 |
| 103 | <u></u> | | | | Special | | | | | | <u> </u> | | | | >3.2 |
| 104 | <u>V</u> | | | | Special | | | | | | | 1 | | | 1 |
| 105 | <u>A</u> | | | | Special | | | | | | | N N | | | 1.6 |
| 106 | ☑ | | | | Special | | | | | | | V | | | 2 |
| 107 | <u>A</u> | | | | - | | | | | | | N N | | | 2.4 |
| | | | | | Special | | | | | | | N N | | | |
| 108 | ☑ | | | | Special | | | | | | | | | | 3.2 |
| 109 | Ø | | | | Special | | | | | | | V | [. 7 | | >3.2 |
| 110 | Ø | | | | Special | | | | | | | | | | 1 6 |
| 111 | ☑ | | | l | Special | | | | | | | | V | | 1.6 |



| | Process Material | | | | | | | Vire | Э | | Se | am p | ositio | n | χ. |
|---------|-------------------|------------------------|---------------|--------------|---------------------|------|------|----------|------|-----|-------------|------------|-------------------------|--------------------|----------------------|
| | | TIG hot wire | TIG cold wire | | | | | Ø | | | Fillet weld | Butt joint | Fillet weld lap joint | Vertical-down weld | Tungsten electrode Ø |
| JOB | TIG | TIG ho | TIG cc | MMA | | 9,0 | 8,0 | 1,0 | 1,2 | 1,6 | | • | P | | ø → - |
| 112 | V | | | | Special | | | | | | | | V | | 2 |
| 113 | ☑ | | | | Special | | | | | | | | V | | 2.4 |
| 114 | | | | | Special | | | | | | | | $\overline{\mathbf{A}}$ | | 3.2 |
| 115 | | | | | Special | | | | | | | | $\overline{\mathbf{A}}$ | | >3.2 |
| 116 | | | | | Special | | | | | | | | | V | 1 |
| 117 | ☑ | | | | Special | | | | | | | | | V | 1.6 |
| 118 | | | | | Special | | | | | | | | | V | 2 |
| 119 | ☑ | | | | Special | | | | | | | | | V | 2.4 |
| 120 | ☑ | | | | Special | | | | | | | | | V | 3.2 |
| 121 | ☑ | | | | Special | | | | | | | | | | >3.2 |
| 122 | TIC | TIG manual/TIG classic | | | | | | | | | | | | | |
| 123 | Classic electrode | | | | | | | | | | | | | | |
| 124 | Re | Reserved | | | | | | | | | | | | | |
| 125 | Re | ser | ved | | | | | | | | | | | | |
| 126 | Re | ser | ved | | | | | | | | | | | | |
| 127 | Ele | ectro | ode | JOI | 3 | | | | | | | | | | |
| 128 | | ser | | | | | | | | | | | | | |
| 129-179 | Fre | ee J | OB: | s or | SCO (e.g. p | lasr | na) | | | | 1 | 1 | | | |
| 180 | | V | | | CrNi | | | | V | | V | | | | 2.4 |
| 181 | | V | | | CrNi | | V | Ø | V | | V | | | | 3.2 |
| 182 | | V | | | CrNi | | V | Ø | V | | V | | | | >3.2 |
| 183 | Ø | V | | | FeSt | | ☑ | ☑ | V | | V | | | | 2.4 |
| 184 | ☑ | V | | | FeSt | | ☑ | ☑ | V | | Ø | | | | 3.2 |
| 185 | ☑ | ☑ | | | FeSt | - | V | <u> </u> | V | | <u> </u> | | | | >3.2 |
| 186 | ☑ | ☑ | | | CuSi | - | | ☑ | | | <u> </u> | | | | 2.4 |
| 187 | <u>_</u> | ☑. | | | CuSi | | | ☑ | | | <u> </u> | | • | Щ | 3.2 |
| 188-207 | | | | s or) on | special cust ly) | ome | er o | rde | r (S | SCC |)/110 | 3 Co | mfort (| with | l |
| 208-215 | | | | s or 3 on | special cust ly) | ome | er o | rde | r (S | CC |)/ele | ctroc | le Con | nfor | t (with |
| 216-254 | Fre | e J | OB: | s or | special cust | ome | er o | rde | r (S | CC |) | | | | |
| 255 | DC | ;- w | ith [| DC+ | · ignition | | | | | | | | | | |
| 256 | Те | st jo | b: 5 | 5 A | to Imax | | | | | | | | | | |

□ not possible

☑ possible



Appendix B 11

11.1 Parameter overview – setting ranges

11.1.1 TIG welding

| Parameter | Displa | ıy | Settir | ng ran | ge | | Comment | | |
|----------------------------|------------|------|----------|--------|----|-------|--|--|--|
| TIG/plasma | | | | | | | | | |
| | Code | Unit | Standard | Min. | | Мах. | | | |
| Gas pre-flow time | [Pr | S | 0,5 | 0 | - | 20 | | | |
| Ignition current AMP% | 1 5E | % | 20 | 1 | - | 200 | % of main current AMP | | |
| Up-slope time | LUP | s | 1,0 | 0,0 | - | 20,0 | | | |
| Pulse time | E 1 | S | 0,01 | 0,00 | - | 20,0 | | | |
| Slope time | £5 / | S | 0,10 | 0,00 | - | 20,0 | Time from main current AMP to secondary current AMP% | | |
| Secondary current AMP% | [2 | % | 50 | 1 | | 200 | % of main current AMP | | |
| Pulse pause time | F 2 | s | 0,01 | 0,00 | - | 20,0 | | | |
| Slope time | £52 | S | 0,10 | 0,00 | - | 20,0 | Period from secondary current AMP% to main current AMP | | |
| Down-slope time | Edn | s | 1,0 | 0,0 | - | 20,0 | | | |
| End current AMP% | l Ed | % | 20 | 1 | - | 200 | % of main current AMP | | |
| Gas post-flow time | GPŁ | S | 8 | 0,0 | - | 40,0 | | | |
| spotArc time | E P | s | 2 | 0,01 | - | 20,0 | | | |
| spotmatic time (5£5) > on) | E P | ms | 200 | 5 | - | 999 | | | |
| spotmatic time (5£5 > 6FF) | E P | s | 2 | 0,01 | - | 20,0 | | | |
| activArc | RRP | | | 0 | - | 100 | | | |
| Up/down speed | שווים | % | 10 | 1 | - | 100 | x0.01% of main current AMP | | |
| Current jump | di | Α | 1 | 1 | - | 20 | | | |
| Pulse balance | 6AL | % | | 1 | - | 99 | Pulsing, metallurgical | | |
| Pulse frequency | FrE | Hz | 50 | 5 | - | 15000 | Pulsing, metallurgical | | |

11.1.2 MMA welding

| Parameter | Display | y | Settir | ng ran | ge | | Comment | | |
|-------------------|------------|------|----------|--------|----|------|---|--|--|
| ММА | Code | Unit | Standard | Min. | | Мах. | | | |
| Hot start current | [hE | % | 120 | 1 | - | 200 | % of main current AMP (set parameter Pb5 to FF) | | |
| Hot start time | EHE | S | 0,5 | 0,0 | - | 10,0 | | | |
| Arcforce | Arc) | | 0 | -40 | - | 40 | | | |
| Pulse frequency | FrE | Hz | 1.2 | 0.2 | - | 500 | | | |
| Pulse balance | ЬЯL | | 30 | 1 | - | 99 | | | |



12 Appendix C

12.1 Overview of EWM branches

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